

Computationally Extendible Order Types

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The candidate confirms that the work submitted is his own and that appropriate credit has been given where reference has been made to the work of others.

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Abstract

In this thesis we consider, from a computability perspective, the question of what order-theoretic properties of a partial order can be preserved under linear extension. It is well-known that such properties as well-foundedness or scatteredness can be preserved, that is, given any well-founded partial order you can find a well-founded linear extension and *mutatis mutandis* for scattered partial orders.

An order type σ is extendible if a partial order that does not embed σ can always be extended to a linear order that does not extend σ . So for example “given any well-founded partial order, you can find a well-founded linear extension” is equivalent to saying that ω^* is extendible. The extendible order types were classified by Bonnet [3] in 1969.

We define notions of computable extendibility and then apply them to investigate the computable extendibility of three commonly used order types, ω^* , $\omega^* + \omega$ and η .

In Chapter 2 we prove that given a computably well-founded computable partial order, you can find a computably well-founded ω -c.e. linear extension, and further that this result doesn't hold for n -c.e. for any finite n . In Chapter 3 we show how to extend these results for linearisations of computable partial orders which do not embed $\zeta = \omega^* + \omega$. In Chapter 4 we prove the analogous results for scattered partial orders.

In memory of Barry Cooper

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Chapter 1

Introduction

1.1 Notations and Conventions

We begin by setting out the notation and conventions that we will be working in, in order to avoid confusion with some of the historical conventions which may differ from the modern standards. We will mostly follow the conventions laid out in Cooper [10], Soare [49] and other standard texts.

We denote the set of natural numbers by $\mathbb{N} = \{0, 1, 2, \dots\}$ and its order type under the usual \leq ordering by ω . We will use lower-case Roman characters to denote natural numbers, and upper-case Roman characters to denote subsets of \mathbb{N} . We will use lower-case Greek characters to denote order types, ω for the order type of the natural numbers, η for the order type of the rational numbers, and a star $*$ to denote a reverse type, so for example ω^* denotes the reverse of the order type of the natural numbers or the order type of the negative integers. We will use \equiv to denote isomorphism between order types.

Given a (possibly partial) function f , we use the notation $f(n)\downarrow$ if f is defined at

n , and $f(n)\uparrow$ if f is not defined at n . If f and g are functions, and the domain on which f is defined is a subset of the domain on which g is defined, and $f(n) = g(n)$ for all n on which f is defined, then we say $f \subseteq g$. If for some n , $f(n)\downarrow \neq g(n)\downarrow$ then we say the functions are incompatible.

We use the standard bijective pairing function $\langle \cdot, \cdot \rangle : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$, $\langle x, y \rangle = \frac{x^2 + 2xy + y^2 + 3x + y}{2}$, and if necessary we can nest it to get a bijection from $\mathbb{N}^i \rightarrow \mathbb{N}$ for any i .

We use the standard listing $\{W_e\}_{e \in \mathbb{N}}$ of computably enumerable sets, where by the Normal Form Theorem, W_e is the domain of φ_e , the e th partial computable function in a standard computable listing of partial computable functions $\{\varphi_e\}_{e \in \mathbb{N}}$. We have the standard approximations $\{W_e[s]\}_{e, s \in \mathbb{N}}$ associated to the W_e . $W_e[s]$ denotes the set of natural numbers enumerated into W_e by the end of stage s of a computation. Turing functionals will be denoted by upper case Greek letters.

1.2 Computability Theory

Computability Theory, also known as Recursion Theory, is based in the study of effectiveness. Intuitively we think of an algorithm as an effective process for calculating a function or deciding a question like whether a number is in a specific set. What it means for a process to be effectively calculable, and whether some algorithms are in some sense more effectively calculable than others, are questions we ask in Computability theory.

The notion of effectively calculable can be formalised in different ways, including “general recursive”¹ (Gödel and Herbrand 1931 [17]), “ λ -definable” (Church 1932 [6])

¹This notion was also just called “recursive”, particularly by Church and Kleene after 1934/5.

1936 [8] 1940 [9])², and “computable”³ (Turing 1936 [52]). These different models of computation were proved to be equivalent by Church and Turing [7] and the idea that they capture the intuitive notion of effectively calculable is known as the Church-Turing Thesis, stated for example in Turing’s PhD thesis [53].

Turing computability, using Turing’s “automatic machines”⁴ provides a useful way of talking about computable functions. We assume familiarity with the technical details of Turing machines and their use, further details can be found in the texts listed at the end of this section.

The functions we consider in computability theory are conventionally functions of natural numbers, with a domain of $A \subseteq \mathbb{N}$ and a codomain of \mathbb{N} . It is useful to distinguish the case when $A = \mathbb{N}$ and functions which are defined on all natural numbers are called *total* functions, and *partial* functions otherwise. When we talk about the computability of a subset $A \subseteq \mathbb{N}$, we identify the set with its characteristic function, the function $f_A : \mathbb{N} \rightarrow \{0, 1\}$ such that

$$f_A(n) = \begin{cases} 1 & \text{if } n \in A \\ 0 & \text{if } n \notin A. \end{cases}$$

And then the computability of A is defined as the computability of f_A . Given the usual equivalence between subsets of \mathbb{N} and binary reals, this also allows us to talk about the computable complexity of individual real numbers, in terms of the oracle strength needed to compute them.

²The original system published in 1932 was shown to be inconsistent by Kleene and Rosser [26], so in 1936 Church published what is now known as the untyped lambda calculus, and in 1940 the simply typed lambda calculus.

³This notion is now known as Turing computable

⁴Turing [52] used the terminology “automatic machines” or “a-machines”. We now know these constructs as “Turing machines”.

The oracle Turing machine, introduced by Turing in 1939 [53] allows us to talk about functionals. Functionals are partial or total functions which range over functions of numbers and return numbers, in an effective sense. The functional $F(\alpha_0, \dots, \alpha_n, \vec{x})$ is a *partial computable functional* if it can be obtained from partial functions $\alpha_0, \dots, \alpha_n$ and the initial functions by composition, primitive recursion and μ -recursion, where the partial functions $\alpha_0, \dots, \alpha_n$ correspond to oracles in the Turing machine implementation of the functional.

Each partial computable functional $F(\alpha_0, \dots, \alpha_n, \vec{x})$, considered as a functional of a variable α_0 , is computable uniformly⁵ in $\alpha_1, \dots, \alpha_n, \vec{x}$, and so we can construct an effective listing of partial computable functionals $\{F_e(\alpha_0)\}_{e \in \mathbb{N}}$. This allows us to list all possible Turing machines, since we can assign a Gödel number n to a Turing machine Ψ , then list the machines Ψ_1, Ψ_2, \dots , which compute F_m for some m . For ease of use, we say that if n is not the Gödel number of a Turing machine, then Ψ_n is a Turing machine running the empty program.

Given such a list of Turing machines, Turing showed that we can find a partial computable functional $F(x, y) = \Psi_x(y)$, which we can use to simulate any of the Turing machines in the list. We call such a machine a *Universal Turing Machine*.

We write $\Psi(B) = A$ to mean that the Turing machine Ψ can compute the set A when given the set B as an oracle, and we use this notion to define the relation $A \leq_T B$ if there exists a Turing machine Ψ such that $\Psi(B) = A$, and we call the relation \leq_T “Turing reducible to”. The relation \leq_T induces an equivalence relation \equiv_T on sets of natural numbers; $A \equiv_T B$ if $A \leq_T B$ and $B \leq_T A$ (so there are Turing functionals Ψ, Ψ' such that $\Psi(A) = B$ and $\Psi'(B) = A$). We call the equivalence classes of this relation *Turing degrees* as defined by Post [39]. Formally, the Turing degree of a set A is

⁵By which we mean that the computation is the same, just with different inputs.

$\text{deg}(A) = \{X \subseteq \mathbb{N} \mid X \equiv_T A\}$, often denoted by \mathbf{a} .

Further, as shown by Post [39] there is an induced partial ordering \leq on the Turing degrees obtained by setting $\mathbf{a} \leq \mathbf{b}$ if there is some $A \in \mathbf{a}$ and $B \in \mathbf{b}$ such that $A \leq_T B$. We can use this partial ordering to define the *Turing degree structure* $\mathcal{D} = (D, \leq)$, which is a major object of study in Computability Theory.

The list of Turing machines allows us to define the halting set $K = \{x \mid \Psi_x(x) \text{ is defined}\}$, which is not computable. Using the list of Turing machines, we can define a corresponding list of sets $W_e = \{n \mid \Psi_e(n) \text{ halts}\}$, which gives us the standard listing of what are called the *computably enumerable* sets. Clearly $K = W_e$ for some $e \in \mathbb{N}$.

Kleene and Post [25] relativised the halting set, $K^A = \{x \mid \Psi_x(A; x) \downarrow\}$. This notion defines the jump operator, K^A is A' , the jump of A , and the $n + 1$ th jump of A is $A^{n+1} = K^{A^n} = (A^n)'$. It naturally follows that the jump of a degree is $\mathbf{a}' = \text{deg}(A')$ and the jump function $f : \mathcal{D} \rightarrow \mathcal{D}, f : \mathbf{a} \mapsto \mathbf{a}'$ is a well defined and strictly increasing function on the Turing degrees. Of particular interest is the degree $\mathbf{0}'$, the degree of the jump of a computable set, which is also the degree of K .

The arithmetical hierarchy of sets of natural numbers classifies the complexity of the formulae needed to define such sets. A formula with only bounded quantifiers is in both the classes Σ_0^0 and Π_0^0 . Then we inductively define the hierarchy as follows, in the manner due to Kleene [22] and (independently) Mostowski [33], using the Prenex Normal Form of Kuratowski and Tarski [27].

- A formula is in the class Σ_n^0 if it is logically equivalent to a formula of the form $\exists \bar{x} \varphi(\bar{x})$, where $\varphi(\bar{x})$ is in the class Π_{n-1}^0 .
- A formula is in the class Π_n^0 if it is logically equivalent to a formula of the form $\forall \bar{x} \varphi(\bar{x})$, where $\varphi(\bar{x})$ is in the class Σ_{n-1}^0 .

Then a set is in the class Σ_n^0 if it can be defined by a Σ_n^0 formula, and similarly for Π_n^0 . The intersection of the classes Σ_n^0 and Π_n^0 is called Δ_n^0 . The Turing computable sets are exactly those in class Δ_1^0 , and the computably enumerable sets are exactly those in Σ_1^0 . The arithmetical hierarchy on degrees is defined in the obvious way, a degree is in Σ_n^0 if it contains a set in Σ_n^0 and the same for Π_n^0 . In this thesis, the superscript 0 will be assumed, and for simplicity of notation will be suppressed.

The degrees below (Turing reducible to) $0'$ are called the *local degrees*, and are exactly those in the class Δ_2 (by Post's Theorem [38]). In general the Δ_{n+1} sets are precisely those Turing reducible to $0^{(n)}$. The sets in the local degrees will be of particular interest in this thesis, and we will need to define a finer-grained hierarchy on these sets.

1.3 The Ershov Hierarchy

The Ershov hierarchy, also known as the difference hierarchy, or the hierarchy of α -c.e. sets, characterises the Δ_2 -definable sets by exploiting the Shoenfield Limit Lemma, which approximates Δ_2 sets in a limit computable way.

Lemma 1.1 (Shoenfield Limit Lemma, 1959 [45]).

A set A is Δ_2 if and only if there is a computable binary function $f : \mathbb{N}^2 \rightarrow \{0, 1\}$ such that for all $n \in \mathbb{N}$ there are cofinitely many stages s at which $\chi_A(n) = f(n, s)$, (where χ_A is the characteristic function of A) that is that $\lim_{s \rightarrow \infty} f(n, s)$ exists and is equal to $\chi_A(n)$.

The n -c.e. hierarchy for finite n was introduced by Putnam (1965 [41]) and Gold (1965 [18]), then it was extended to transfinite α -c.e. by Ershov (1968-70 [13] [14] [15]).

Intuitively we think of a c.e. set as a set which can be approximated by a function $A(s, x) : \mathbb{N}^2 \rightarrow \{0, 1\}$, where $A(0, x) = 0$ for all x , i.e. we start by guessing that $x \notin A$ at stage 0, then if at some time t we enumerate x into A , we have $A(t, x) = 1$, and $A(t', x) = 1$ for all $t' > t$. Notice that the approximation changes at most once for a given x as s increases.

If we allow the approximation to change more than once, we can approximate a larger class of sets, and for each n , we call the class of sets which can be approximated by allowing the approximation as discussed above to change up to n times for each x , the class of n -c.e. sets. This informally defines the finite levels of the Ershov hierarchy, and we can give a formal definition as follows.

Definition 1.2.

A set $A \subseteq \mathbb{N}$ is n -computably enumerable if either $n = 0$ and $A = \emptyset$ or $n > 0$ and there are c.e. sets $R_0 \supseteq R_1 \supseteq \dots \supseteq R_{n-1}$ such that,

$$A = \bigcup_{i=0}^{\lfloor \frac{n-1}{2} \rfloor} (R_{2i} \setminus R_{2i+1}) \quad (\text{if } n \text{ is odd then set } R_n = \emptyset).$$

Or equivalently, if there is a computable binary function $f : \mathbb{N}^2 \rightarrow \{0, 1\}$ such that for all x , $f(0, x) = 0$ and $A(x) = \lim_{s \rightarrow \infty} f(s, x)$, and $|\{s \mid f(s+1, x) \neq f(s, x)\}| \leq n$.

Following the notation introduced by Ershov, we call the class of n -c.e. sets level Σ_n^{-1} of the Ershov hierarchy, with the complements of those sets constituting level Π_n^{-1} and the intersection of Σ_n^{-1} and Π_n^{-1} is called Δ_n^{-1} .

It is obvious that $\Sigma_n^{-1} \subset \Sigma_{n+1}^{-1}$, since any n -c.e. set is also an $(n+1)$ -c.e. set.

But the inclusion is strict because for every $n > 0$ there is an $(n + 1)$ -c.e. set which is not n -c.e., and which has a complement which is $(n + 1)$ -c.e. and not n -c.e., so $\Sigma_n^{-1} \subsetneq \Sigma_{n+1}^{-1}$ and $\Pi_n^{-1} \subsetneq \Pi_{n+1}^{-1}$. Then obviously we have the hierarchy theorem that for all $n > 0$, $\Sigma_n^{-1} \cup \Pi_n^{-1} \subsetneq \Sigma_{n+1}^{-1} \cap \Pi_{n+1}^{-1}$.

We define Σ_ω^{-1} , the first infinite level of the Ershov hierarchy, in a similar way.

Definition 1.3.

A set $A \subseteq \mathbb{N}$ belongs to level Σ_ω^{-1} of the Ershov hierarchy, if there is an ω -sequence of uniformly c.e. sets $\{R_e\}_{e \in \omega}$ such that $A = \bigcup_{n=0}^{\infty} (R_{2n+1} \setminus R_{2n})$.

Then Π_ω^{-1} is the class of complements of sets in Σ_ω^{-1} , and $\Delta_\omega^{-1} = \Sigma_\omega^{-1} \cap \Pi_\omega^{-1}$, and we describe the sets in Δ_ω^{-1} as ω -c.e. The ω -c.e. sets can be characterised in a number of different ways, which may be more or less useful depending on the situation. We present some of these characterisations below, following Arslanov [1].

Theorem 1.4 (Arslanov [1]).

Let $A \subseteq \mathbb{N}$, then the following are equivalent:

1. A is ω -c.e.
2. There exists an ω -sequence of uniformly c.e. sets $\{R_e\}_{e \in \omega}$ such that $\bigcup_{e \in \mathbb{N}} R_e = \mathbb{N}$ and $A = \bigcup_{n=0}^{\infty} (R_{2n+1} \setminus R_{2n})$.
3. There exist computable functions f, g such that for all $s, x \in \mathbb{N}$, $A(x) = \lim_{s \rightarrow \infty} g(s, x)$ and $|\{s \mid g(s, x) \neq g(s + 1, x)\}| \leq f(x)$.
4. There is a partial computable function φ such that for all $x \in \mathbb{N}$, $A(x) = \varphi(\mu t(\varphi(t, x) \downarrow), x)$.
5. A is tt-reducible to $\mathbf{0}'$.

For further background on Computability Theory we refer the reader to standard texts such as Cooper [10], Nies [35], Odifreddi [36] [37] and Soare [49]. For further details on the Ershov hierarchy we refer to Arslanov [1], Ershov [13] [14] [15] and Stephan, Yang and Yu [50].

1.4 Priority Arguments

Priority arguments are one of the key tools of computability theory, used in proofs in all areas of computability. They are used to construct a structure (or several structures) with some particular properties in a computable way. The idea is to break the property down into infinitely many requirements, and then come up with a strategy to satisfy each requirement individually, and then a method to combine all of the strategies. In order to deal with clashes when combining the strategies, we put a priority ordering on the requirements, so that if at any point two or more requirements are in conflict then the requirement with highest priority takes precedence. Once the construction ends and the argument is completed, we have a verification to show that the argument is sound, and the construction satisfies the properties that we want.

Priority arguments originated with Kleene and Post [25] who gave the first use of this method in the proof of Theorem 1.5.

Theorem 1.5 (Kleene and Post 1954 [25]).

There exist incomparable degrees below $0'$

Note that in this argument each requirement is satisfied without injuring any other requirements. This is the simplest type of priority argument, a more complicated argument allows requirements to injure requirements of lower priority, by which we mean cause them to become unsatisfied if they have been satisfied before the higher priority

requirement. This type of priority argument was independently developed by Friedberg [16] and Muchnik [34] to prove Theorem 1.6.

Theorem 1.6 (Friedberg 1957 [16] and Muchnik 1956 [34]).

There exist incomparable c.e. degrees.

There is an important distinction to be drawn between arguments which allow requirements to be injured infinitely often, and arguments which only allow finite injury. The theorems in this thesis will only use finite injury priority arguments, so we will not go into detail on how infinite injury works. To give an example of the use of the finite injury priority method related to linear orderings, we prove the following well-known theorem, following the proof as presented by Downey [11]. This is not the simplest proof, it is possible to prove this result without using the priority method, but we hope this will be illustrative of how it works.

We first need to define the concept of a mathematical structure (in this case a linear order) being *1-computable*. A structure A is 1-computable if any logical sentence with one quantifier can be effectively decided in the structure. Note that this is stronger condition than A being *computable*, which just means that the order relation is computable.

Theorem 1.7 (Folklore, see for example Downey [11] Theorem 2.11).

There is a computable linear ordering A of order type ω with $S(x)$, the successor function, not computable. Hence, A is not 1-computable since the adjacency relation is not computable.

Proof. We build a computable linear order A as the union of finite linear orderings $\cup_s A_s$. The two properties that we want A to have are that it has order type ω and $S(x)$ is not computable in A . We can split each property into infinitely many requirements. Labelling the elements of A as a_0, a_1, a_2, \dots , and using a standard computable listing of partial computable functions $\{\varphi_e\}_{e \in \mathbb{N}}$, we get the requirements as follows, for each $e \in \mathbb{N}$.

N_e : a_e has finitely many predecessors.

P_e : φ_e is not the successor function on A .

Where clearly the N requirements ensure A has order type ω , and the P requirements ensure that $S(x)$ is not computable.

In order to satisfy P_e , we choose some $x = x(e)$ and wait for a stage s such that $\varphi_{e,s}(x) \downarrow$. If this never happens then φ_e is not total and P_e is satisfied. If there is some s such that $\varphi_{e,s}(x) \downarrow$ then we place a new point between x and $\varphi_e(x)$, ensuring that $\varphi_e(x) \neq S(x)$. This strategy for satisfying P_e is called the *basic module* for P_e .

This has the potential to cause problems for N_i , as if infinitely many P requirements are allowed to place new points below a_i then N_i will not be satisfied. In order to avoid this, we use the priority ordering $N_0 \succ P_0 \succ N_1 \succ P_1 \succ N_2 \succ P_2 \succ \dots$. Thus only finitely many P requirements have higher priority than a given N requirement N_i , and so only finitely many can place a new point below a_i . If we ensure that each P_e with $e <_{\mathbb{N}} i$ only injures N_i finitely many times, that is only places finitely many new points below a_i , then N_i will be satisfied.

The strategy we use to combine the basic modules for the P_e is just to ensure that we choose $x(e)$ so that it is not below a_i for $i \leq_{\mathbb{N}} e$. Then P_e will not add a predecessor of a_i if $i \leq_{\mathbb{N}} e$. In the construction we will say that P_e *requires attention* at stage $s + 1$ if either P_e has not chosen an element $x(e)$, or P_e has chosen $x(e)$ and $\varphi_{e,s}(x(e)) \downarrow$ and $\varphi_{e,s}(x(e)) = S(x(e))$.

The construction proceeds by stages. At Stage 0, we set $A_0 = \{a_0\}$. At the start of stage $s + 1$, we have \leq_{A_s} as some linear order on the set $\{a_0, \dots, a_s\}$. We search for the least $e \leq s$ such that P_e requires attention. We know that there will be at least one

P_e with $e \leq s$ which requires attention, as we cannot have chosen $x(e)$ for $e = s$. If P_e requires attention because there is no $x(e)$, then define A_{s+1} by placing a_{s+1} above all a_i for $i <_{\mathbb{N}} s + 1$ and declare that $x(e) = a_{s+1}$. Alternatively, if P_e requires attention because $\varphi_{e,s}(x(e)) \downarrow$ and $\varphi_{e,s}(x(e)) = S(x(e))$ then define A_{s+1} by placing a_{s+1} between $x(e)$ and $S(x(e))$. Then proceed to Stage $s + 2$.

It is clear that each P_e requires attention at most twice, each time adding one element to the linear order. Hence, each N_i requirement will be satisfied because only finitely many points can be added as predecessors to a_i , since only P_e for $e < i$ can add such points. This means that N_i can only be injured finitely often, and therefore all the requirements will be satisfied, and A will have the desired properties. \square

1.5 Order Theory

The theory of ordering is based on the highly intuitive notion of some numbers being bigger than others. If we abstract this notion to a general notion of an order on a set, we can define an ordering \mathcal{P} as a set P equipped with a binary relation \leq_P with the following properties. We choose here for convenience to use a non-strict ordering, which conforms to the usual notion of \leq , rather than a strict order which conforms to the notion of $<$.

- Reflexivity, $\forall p \in P, p \leq_P p$.
- Antisymmetry, $\forall p, q \in P$, if $p \leq_P q$ and $q \leq_P p$ then $p = q$.
- Transitivity, $\forall p, q, r \in P$, if $p \leq_P q$ and $q \leq_P r$ then $p \leq_P r$.

These properties define a *partial order*, and if we further require that any two elements are comparable, then we define a *linear order*, also known as a total order.

In general partial orders are defined on any set, but for the purposes of this thesis we will only be using countable domains, in particular \mathbb{N} or subsets of \mathbb{N} .

An *order type* is a equivalence class under order isomorphism of partial orders, though we will often refer to it as if it is a partial order of that type. Order types will be denoted by lower case Greek letters, for example, ω is the order type of the natural numbers. Ordinals are a subset of order types, and we will use an extension of ordinal arithmetic on order types.

If σ and τ are order types, then $\sigma + \tau$ is the order type formed by concatenation of σ and τ , and $\sigma\tau$ is the order type formed by replacing every point in τ by a copy of σ . Also we denote the reverse ordering of σ by σ^* .

There are several properties of orderings which we will be concerned with in this thesis and which I will introduce now. The most well-known property is that of being well-founded, this means that every non-empty chain of P has a \leq_P -minimal element. Equivalently, we say that an ordering is *well-founded* if it contains no infinite descending chain, that is, it does not embed ω^* , the order type of the negative integers.

Another key property of orderings is that of being scattered. An ordering is *scattered* if it contains no dense chain, with density here being defined as follows. If $\mathcal{P} = (P, \leq_P)$ is a partial ordering, and given a chain $Q \subseteq P$, then Q is dense in P if for all $p, q \in Q$ with $p \leq_P q$, there is some $r \in Q$ such that $p <_P r <_P q$. Equivalently we can say an ordering is scattered if it does not embed η , the order type of the rational numbers.

We say a linear order \mathcal{L} is *indecomposable* if whenever we can write $\mathcal{L} = \mathcal{A} + \mathcal{B}$ for some linear orderings \mathcal{A}, \mathcal{B} , either \mathcal{A} or \mathcal{B} embeds \mathcal{L} . We say \mathcal{L} is *right-indecomposable* if whenever $\mathcal{L} = \mathcal{A} + \mathcal{B}$ and \mathcal{B} is not empty, then \mathcal{B} embeds \mathcal{L} . Similarly we say \mathcal{L} is

left-indecomposable if whenever $\mathcal{L} = \mathcal{A} + \mathcal{B}$ and \mathcal{A} is not empty, then \mathcal{A} embeds \mathcal{L} .

We call a partial order $\mathcal{P} = (P, \leq_P)$ *computable*, if P is a computable subset of \mathbb{N} and \leq_P is a computable subset of \mathbb{N}^2 , using a suitable coding. Then we can classify non-computable orderings by the complexity of the order relation, as all orderings we will discuss in this thesis will have a computable set as the domain, in fact we will mostly consider orderings on \mathbb{N} .

1.6 Extensions

Given a partial order $\mathcal{P} = (P, \leq_P)$, we say that $\mathcal{L} = (L, \leq_L)$ is a linear extension, or linearisation of \mathcal{P} , if \mathcal{L} is a linear order, $P = L$ and $\leq_P \subseteq \leq_L$. We know that due to an old theorem of Szpilrajn, linear extensions always exist, and in fact this can be effectivised.

Theorem 1.8 (Szpilrajn 1930 [51]).

Every partial order has a linear extension.

Theorem 1.9 (Folklore, see for example Downey 1998 [11]).

Every computable partial order has a computable linear extension.

There has been a lot of work in the area of preservation under linearisation of various properties of partial orders such as those discussed above. Considerable work was done here by Bonnet, Pouzet, Jullien, Galvin, McKenzie and others (see [5]) on the question of whether partial orders without a countable subordering of a certain order type must always have a linear extension which also has no suborderings of that type. If an order type can be avoided in such a way, then we call it extendible.

Definition 1.10.

If α is a countable order type, we say α is *extendible* if any partial order \mathcal{P} which does not embed α can be extended to a linear order \mathcal{L} which does not embed α .

This culminated in the complete classification of countable extendible order types by Bonnet in 1969 [3]. This includes the order type ω^* , the avoidance of which makes a partial order well-founded, and the order type η , the avoidance of which makes a partial order scattered.

Definition 1.11.

We define a family of order types, by transfinite induction over the countable ordinals, i.e. the ordinals below ω_1 .

- $\pi_1 = \omega$.
- For a successor ordinal $\alpha + 1 < \omega_1$, $\pi_{\alpha+1} = \pi_\alpha^* \omega$.
- For a limit ordinal $\lambda < \omega_1$, $\pi_\lambda = \sum_{\alpha < \lambda} \pi_\alpha^*$.

Theorem 1.12 (Bonnet 1969 [3]).

A countable order type α is extendible if and only if:

- $\alpha \equiv \eta$, or
- $\alpha \equiv \pi_\nu$ for some $\nu < \omega_1$, or
- $\alpha \equiv \pi_\nu^*$ for some $\nu < \omega_1$, or
- $\alpha \equiv \pi_\nu^* + \pi_\nu$ for some $\nu < \omega_1$.

We must note that the definition of partial order that was used here is not the same as ours, in particular Bonnet considered partial orders over any set as the domain, not just partial orders on countable domains. If we restrict to partial orders on a countable domain, then we get a different classification, as proved by Jullien [21]. We use the formulation of Theorem 1.15 given by Montalbán [32] rather than Jullien's original theorem, but it is equivalent, as Montalbán showed.

Definition 1.13.

A linear order type α is *weakly extendible*, when α is countable and any countable partial order that does not embed α can be extended to a linear order that does not embed α .

Definition 1.14. A segment \mathcal{B} of a linear ordering $\mathcal{L} = \mathcal{A} + \mathcal{B} + \mathcal{C}$ is *essential* if whenever we have $\mathcal{L} \leq \mathcal{A} + \mathcal{B}' + \mathcal{C}$ for some linear ordering \mathcal{B}' , then it must be the case that $\mathcal{B} \leq \mathcal{B}'$.

Theorem 1.15 (Jullien 1969 [21]).

A scattered linear ordering \mathcal{L} is extendible if and only if it does not have an essential segment \mathcal{B} such that

- $\mathcal{B} = \mathcal{R} + \mathcal{Q}$, where \mathcal{R} is right-indecomposable and \mathcal{Q} is left-indecomposable, or
- $\mathcal{B} = 2$.

There has been a lot of work carried out on linear extensions of partial orders, other than concerning extendible order types. We give some examples here to show the context for the work on extendible types. We are still concerned here with classes of partial orders which have particular properties, and whether or not they can be guaranteed to have linear extensions with those properties, or possibly other properties.

In some unpublished notes, Miller [31] proved some interesting results about the computational power of scattered extensions, in particular the existence of scattered partial orders such that any scattered extensions can compute various sets.

Definition 1.16.

Given sets A and B , a *separator* of A and B is a superset of A which is disjoint from B .

Theorem 1.17 (Miller 2015 [31]).

Let A, B be disjoint Σ_1^1 sets. There is a scattered computable partial order such that any scattered linear extension computes a separator of A and B .

Theorem 1.18 (Miller 2015 [31]).

Let A, B be disjoint c.e. sets. There is a scattered computable partial order such that any linear extension either computes a suborder of itself of type η or computes a separator of A and B .

Theorem 1.19 (Miller 2015 [31]).

Let A, B be disjoint Σ_2^0 sets. There is a scattered computable partial order such that any (classically) scattered linear extension computes a separator of A and B .

Pouzet and Rival [40] investigated extensions of partial orders with the family of properties around chain-completeness.

Definition 1.20.

We say a linearly ordered subset (chain) of a partial order is *saturated* if no element of the partial order between two elements of the chain can be added to the subset without losing the property of being linearly ordered. A stronger property is a chain being *maximal*, which is when no element can be added without losing the property of being linearly ordered, even at the top or bottom of the subset.

Definition 1.21.

We say a partial order \mathcal{P} is *chain-complete* if every maximal chain of \mathcal{P} is complete, that is, every subchain of a maximal chain has both an infimum and a supremum. We say \mathcal{P} is *locally chain-complete* if every interval in \mathcal{P} is chain-complete. If \mathcal{P} is a chain and it is locally chain-complete then we call it *locally complete*.

Theorem 1.22 (Pouzet and Rival 1981 [40]).

- Every locally chain-complete ordered set in which all antichains are finite has a locally complete linear extension.
- Every countable, locally chain-complete partially ordered set has a locally complete linear extension.

In response to an unpublished question of Łoś, Rutkowski found some necessary conditions and some sufficient conditions for a partial order to have a linear extension of order type η .

Theorem 1.23 (Rutkowski 1996 [44]).

- If \mathcal{P} is a partial order which has a linear extension of order type η , then \mathcal{P} contains an infinite antichain or a nontrivial dense saturated chain.
- If \mathcal{P} is a countable partially ordered set which contains a maximal chain \mathcal{C} of order type η , such that for each $p \in \mathcal{C}$, the set $\{q \in P \mid \forall c \in \mathcal{C}, (c <_P p \iff c <_P q \text{ and } p <_P c \iff q <_P c)\}$ is either equal to $\{p\}$ or has an extension of order type η , then \mathcal{P} has a linear extension of order type η .
- If \mathcal{P} is a countable partially ordered set which satisfies the property that if \mathcal{X}, \mathcal{Y} are finite antichains in \mathcal{P} such that no element of \mathcal{X} is \leq_P -above any element of \mathcal{Y} , then there exists an element $p \in P$ which is neither in the upward cone of \mathcal{X} or the downward cone of \mathcal{Y} . Then \mathcal{P} will have a linear extension of order type η . Moreover \leq_P is the intersection of all such extensions.

Slaman and Woodin further investigated the question of when a partial order has a linear extension of order type η , and showed that it has no easy answer.

Definition 1.24. If X is a subset of \mathbb{N} , then consider $\{e\}^X$ as a suborder of $\omega^{<\omega}$ and define

$$\mathfrak{L}(X) = \{e \mid \{e\}^X \text{ is a partial order on } \mathbb{N} \text{ and has a linearisation of order type } \eta\}.$$

Then let $\mathfrak{L} = \{\langle e, X \rangle \mid e \notin \mathfrak{L}(X)\}$.

Theorem 1.25 (Slaman and Woodin 1998 [48]).

There is a computable function f such that for all e, X , $\{e\}^X$ is a well-founded subtree of $\omega^{<\omega}$ if and only if $f(e) \notin \mathfrak{L}(X)$.

By a theorem of Kleene [24], the collection of well-founded subtrees of $\omega^{<\omega}$ is Π_1^1 -complete hence, \mathfrak{L} is a complete Σ_1^1 -predicate, and therefore not a Borel set.

In model theory, Ramakrishnan and Steinhorn [42] extending work of Macpherson and Steinhorn [30] proved the following theorem concerning classes of first-order structures in which definable partial orders have definable linear extensions.

Theorem 1.26 (Ramakrishnan and Steinhorn 2014 [42]).

Let $\mathcal{M} = (M, <, \dots)$ be a first-order structure which is weakly o-minimal, o-minimal, quasi-o-minimal, well-ordered, or elementarily equivalent to a structure with one of those properties, in which the symbol $<$ is a linear order on M . Then if $\mathcal{P} = (P, \prec)$ is a partial order on a subset $P \subseteq M^n$ for some n which is definable in \mathcal{M} , then \mathcal{P} will have a linear extension definable in \mathcal{M} .

1.7 Reverse Mathematics

There has also been a lot of recent interest in the proof-theoretic content of the theorems about extendibility of order types, investigated using the methods of reverse mathematics. The idea is to determine, for a given theorem, the minimal axiomatic system which is sufficient to prove it. In particular we consider the strength of set comprehension needed to prove the theorem. A comprehension scheme is the collection of axioms $\exists X \forall n (n \in X \leftrightarrow \varphi(n))$, for all formulae φ in some particular class.

It is the size of the class of formulae needed which we use to classify the strength of the theorem. Typically classes used are defined by allowable quantifier depth, we consider for example Δ_1^0 -comprehension and Π_1^1 -comprehension amongst others, but other measures of formula complexity are also used.

As a base, we use the finite axioms of Peano Arithmetic (i.e. PA without the induction schema) along with the Σ_1^0 -induction scheme, which means that for all Σ_1^0 formulae φ , $(\varphi(0) \wedge \forall x (\varphi(x) \rightarrow \varphi(x+1))) \rightarrow \forall n \varphi(n)$.

On top of this base system, Simpson [47] describes five successively stronger systems, which are generally known as the *Big Five* (see, for example, Hirschfeldt [19]). These systems are all frequently used in reverse mathematics. The list below gives the axioms which need to be added to the base system to get each of the Big Five, and are listed in order of strictly increasing proof-theoretic strength.

It turns out that many classical theorems are equivalent to one of the above Big Five systems, and much work in reverse mathematics involves proving that a given theorem is weaker, stronger or equivalent to one of the above. Significant work has been done on placing the theorems which state the extendibility of certain key order types in the reverse mathematics classification, although precise equivalences have not been found in all cases.

Recursive comprehension axiom	RCA_0	$\exists X \forall n (n \in X \leftrightarrow \varphi(n))$ for Δ_1^0 formulae φ .
Weak König's Lemma	WKL_0	Every infinite binary tree has an infinite path.
Arithmetical comprehension axiom	ACA_0	$\exists X \forall n (n \in X \leftrightarrow \varphi(n))$ for arithmetical formulae φ .
Arithmetical transfinite recursion	ATR_0	Any arithmetical operator can be iterated transfinitely along any countable well-order.
Π_1^1 comprehension axiom	$\Pi_1^1\text{-CA}_0$	$\exists X \forall n (n \in X \leftrightarrow \varphi(n))$ for Π_1^1 formulae φ .

The research that has been conducted into the question of determining the proof-theoretic strength of the statement of the extendibility of various order types can be summarised as follows.

Theorem 1.27 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

- “ ω^* is extendible” is provable in ACA_0 .
- “ ω^* is extendible” proves WKL_0 over RCA_0 .
- “ ω^* is extendible” is not provable in WKL_0 .

Theorem 1.28 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

- “ η is extendible” is provable in $\Pi_1^1\text{-CA}_0$.⁶
- “ η is extendible” is not provable in WKL_0 .

Theorem 1.29 (J. Miller 2015 [31]).

- “ η is extendible” implies WKL_0 over RCA_0 .
- “ η is extendible” implies ATR_0 over $\Sigma_1^1\text{-CA}_0$.

Theorem 1.30 (Montalbán 2006 [32]).

- “ η is extendible” is provable in ATR_* .⁷

Theorem 1.31 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

- “ ζ is extendible” is equivalent to ATR_0 over RCA_0 .

Another interesting reverse mathematical result in the field of extendible order types involves Jullien’s classification of weakly extendible order types (Theorem 1.15) and Fraïssé’s conjecture⁸. We recall Jullien’s result from Theorem 1.15 and the statement of Fraïssé’s conjecture below.

⁶Downey et. al. actually proved that “ η is extendible” is provable in $\Pi_2^1\text{-CA}_0$, which was then improved to $\Pi_1^1\text{-CA}_0$ with Becker, in the same paper.

⁷ ATR_* is the system ATR_0 with Σ_1^1 -induction.

⁸Proved by Laver 1971 [28].

Theorem 1.32 (Fraïssé’s conjecture, Laver 1971 [28]).

The class of countable linear orderings, quasiordered by the relation of embeddability, contains no infinite descending chain and no infinite antichain.

Theorem 1.33 (Montalbán 2006 [32]).

Jullien’s theorem is equivalent to Fraïssé’s conjecture over $\text{RCA}_0 + \Sigma_1^1\text{-IND}$.

It should be noted that Shore [46] had previously proved that Fraïssé’s conjecture is proof-theoretically strong, indeed it implies ATR_0 over RCA_0 , so Montalbán’s result shows that Jullien’s theorem is also strong.

1.8 Thesis Outline

In this thesis we consider the computable content of Bonnet’s Theorem (Theorem 1.12), extending previous work of Rosenstein, Statman and Kierstead [43], Downey, Hirschfeldt, Lempp and Solomon [12] and Cooper, Lee and Morphett [29].

The question is whether given a computable partial order which does not computably embed some extendible computable order type, what is the lowest level of complexity at which we can always find a linear extension which also does not computably embed that order type?

In Chapter 2 we look at well-founded orderings, i.e. orderings which do not embed ω^* , and improve the lower bound proved by Rosenstein and Kierstead to show that the upper bound previously proved by Cooper, Lee and Morphett is the best possible result.

Theorem 1.34 (Theorem 2.8, Theorem 2.14, Corollary 2.19).

If \mathcal{P} is a computably well-founded computable partial order, then \mathcal{P} has a computably well-founded ω -c.e. linear extension. However, there is a computably well-founded

computable partial order \mathcal{P} which has no computably well-founded n -c.e. linear extension for any $n \geq 1$.

In Chapter 3 we consider the order type $\zeta = \omega^* + \omega$ and prove an analogous result for n -c.e. extensions, but then show that this in fact extends to ω -c.e. and Δ_2 extensions.

Theorem 1.35 (Theorem 3.9, Theorem 3.5).

There is a computable partial order \mathcal{P} which does not computably embed ζ and has no n -c.e. linear extension which does not computably embed ζ for any $n \geq 1$. There is a computable partial order \mathcal{P} which does not computably embed ζ and has no ω -c.e. linear extension which does not computably embed ζ . There is a computable partial order \mathcal{P} which does not computably embed ζ and has no Δ_2 linear extension which does not computably embed ζ .

In Chapter 4 we consider the case of scattered orderings, i.e. orderings which do not embed η . We show that the order type η behaves similarly to ω^* .

Theorem 1.36 (Theorem 4.14, Theorem 4.18, Corollary 4.22).

If \mathcal{P} is a computably scattered computable partial order, then \mathcal{P} has a computably scattered ω -c.e. linear extension. However, there is a computably scattered computable partial order \mathcal{P} which has no computably scattered n -c.e. linear extension for any $n \geq 1$.

Chapter 2

Well-founded orderings

We consider what is known about linearisations of well-founded partial orders, and the computable content of those theorems in the Ershov hierarchy. We look at the previously proved bounds on the complexity of linearisations which preserve well-foundedness, and prove a new lower bound, closing the gap to give a sharp result.

2.1 Background

We know from the Szpilrajn Extension Theorem (Theorem 1.8) that any partial order has a linear extension, so it is an obvious line of inquiry to ask whether a partial order which has a particular order-theoretic property must have a linear extension which shares that property. The most well known order theoretic property is probably that of well-foundedness. It is often defined as the property that any suborder will have minimal elements, but here we will use the following equivalent definition.

Definition 2.1.

A partial order \mathcal{P} is *well-founded* if there is no infinite descending sequence under $\leq_{\mathcal{P}}$, i.e. \mathcal{P} contains no subordering of type ω^* .

Classically, it is known that well-foundedness can be preserved by linearisation, due to a result of Bonnet. This is relatively easy to see, as we demonstrate below.

Theorem 2.2 (Bonnet 1969 [3]).

Every well-founded partial order $\mathcal{P} = (P, \leq_P)$ has a well-founded linear extension. I.e. ω^* is extendible.

Proof. Inductively define a partition of P as follows: let P_0 be the set of \leq_P -minimal elements of P , then let P_α be the set of \leq_P -minimal elements of $P \setminus \bigcup_{\beta < \alpha} P_\beta$. This process will terminate for some $P_\delta = \emptyset$. Clearly each P_α is an antichain in \mathcal{P} , so let $\mathcal{L}(P_\alpha)$ be a well-founded linear extension of P_α , then $\sum_{\alpha < \delta} \mathcal{L}(P_\alpha)$ is a well-founded linear extension of \mathcal{P} . \square

Kierstead and Rosenstein [43] demonstrated a version of Bonnet's result for computable orderings, but at the same time Rosenstein and Statman [43] showed that a version with a computable version of the well-foundedness property does not hold. We use the notion of computable well-foundedness, as introduced by Rosenstein.

Theorem 2.3 (Kierstead and Rosenstein 1984 [43]).

Every well-founded computable partial order has a well-founded computable linear extension.

Proof. Suppose $\mathcal{P} = (P, \leq_P)$ is a computable partial order, and that it is well-founded. Then we construct a computable linear extension $\mathcal{L} = (P, \leq_L)$ of \mathcal{P} as follows.

Suppose at the start of stage n we have already defined whether $a \leq_L b$ holds for all $a, b <_{\mathbb{N}} n$, and $\leq_{L, n-1}$ is a linear ordering of $\{1, 2, \dots, n-1\}$ which extends $\leq_P \upharpoonright_{n-1}$. At stage n we must decide where n should be placed in the ordering that we are constructing. We choose to place n as high as possible whilst extending the ordering of \mathcal{P} , that is we place it immediately below the $\leq_{L, n-1}$ -smallest number which is \leq_P -greater

than n .

In Figure 2.1 we depict the linear order on the first $n - 1$ elements, and have circled the elements which are \leq_P -greater than n and squared the elements which are \leq_P -less than n . The arrow then shows where n will be placed in the linearisation.



Figure 2.1: Construction of the linear extension

It is clear that this method will produce a computable linear extension of \mathcal{P} . Now suppose that \mathcal{L} is not well-founded, so there exists some infinite descending chain $x_0 >_L x_1 >_L x_2 >_L \dots$. Without loss of generality we can assume that $x_0 <_{\mathbb{N}} x_1 <_{\mathbb{N}} x_2 <_{\mathbb{N}} \dots$ and we know that for all $i <_{\mathbb{N}} j$ we must have either $x_i >_P x_j$ or $x_i \mid_P x_j$. Since we assume that \mathcal{P} is well-founded, by Ramsey's theorem we can assume that $x_i \mid_P x_j$ for all i, j , by ignoring some of the sequence if necessary.

Therefore, for each $i > 0$ we know that $x_i \mid_P x_0$, $x_i >_{\mathbb{N}} x_0$ and $x_i <_L x_0$, and hence there must be some y_i such that $y_i <_{\mathbb{N}} x_0$ and $x_i <_P y_i <_L x_0$. Since each $y_i <_{\mathbb{N}} x_0$ there must be some $y_0 <_{\mathbb{N}} x_0$ such that $x_i <_P y_0 <_L x_0$ for infinitely many x_i , and hence we may assume that y_0 is chosen minimally with this property, and by eliminating other x_i we may thus assume that $x_i <_P y_0 <_L x_0$ for all $i > 0$.

If we continue to inductively define y_i for all $i \in \mathbb{N}$, we build a sequence y_0, y_1, y_2, \dots such that for all $i, j \in \mathbb{N}$ such that $i >_{\mathbb{N}} j$, we have $x_i <_P y_j <_L y_j$ and that all the y_j are chosen minimally (i.e. such that there is no $z <_{\mathbb{N}} y_j$ with $x_i <_P z$ for infinitely many x_i). We know that none of the y_i are equal and in fact $y_0 <_{\mathbb{N}} y_1 <_{\mathbb{N}} y_2 <_{\mathbb{N}} \dots$, because of the minimality and since $y_i <_L x_i <_P y_j$ for all $i >_{\mathbb{N}} j$.

Since $y_{j+1} <_L x_{j+1} <_P y_j$, we have $y_{j+1} <_L y_j$. If $y_{j+1} \mid_P y_j$, then since $y_{j+1} >_{\mathbb{N}} y_j$, there must be some $z <_{\mathbb{N}} y_j$ such that $y_{j+1} <_P z <_L y_j$. But then $x_i <_P y_{j+1} <_P z <_L y_j$ for all $i >_{\mathbb{N}} j + 1$, which contradicts the minimality of the choice of y_j . Hence, $y_{j+1} <_P y_j$ for all j , which contradicts the well-foundedness of \mathcal{P} .

Therefore, no such chain $x_0 >_L x_1 >_L x_2 >_L \cdots$ exists and \mathcal{L} must be well-founded. \square

This theorem is only partially effective. We can also effectivise the embedding of ω^* , by using the following definition instead of just wellfoundedness.

Definition 2.4.

A partial order \mathcal{A} is defined to be *computably well-founded* if there is no computable infinite descending sequence under $\leq_{\mathcal{A}}$, i.e. \mathcal{A} contains no computable subordering of type ω^* . Equivalently, if any computable suborder has a least element.

Theorem 2.5 (Rosenstein and Statman 1984 [43]).

There is a computably well-founded computable partial order which does not have a computably well-founded computable linear extension.

Proof. The counterexample that we construct is a computable binary tree \mathcal{T} known as a Kleene Tree [23]. We start by computably generating the full downward-branching binary tree, labelling the nodes by natural numbers coding binary strings, as in Figures 4.11 4.11. And simultaneously enumerating all computably enumerable sets W_e . If at some time we have enumerated the first e elements of W_e and they form a descending chain in the tree, then we “kill” the node corresponding to the e th element of W_e , by which we mean that no new nodes will be added below it, so that the tree below that point remains finite. Note that this construction doesn’t halt at a finite stage, because at each level of the tree there are more nodes than c.e. sets that can possibly kill nodes at that level. So the tree constructed will be infinite.

This tree, whilst by König's Lemma, clearly contains an infinite descending sequence, by construction cannot contain a computable infinite descending sequence, and is therefore computably well-founded.

Now, let \mathcal{L} be any computable linear extension of \mathcal{T} . We will show that \mathcal{L} is not computably well-founded by constructing a computable infinite descending chain in \mathcal{L} .

Let x_0 be the root of the tree, and P_0 be the set of immediate \mathcal{T} -predecessors of x_0 . At the beginning of stage n , we assume we have already defined a sequence of elements x_0, x_1, \dots, x_{n-1} and a set P_{n-1} . We further assume as part of the induction hypothesis that the sequence x_0, x_1, \dots, x_{n-1} forms a terminal part of the tree, that is if y is above x_i in the tree, then $y = x_j$ for some $j < i$, and that P_{n-1} consists of all the of the immediate \mathcal{T} -predecessors of all of the x_i , apart from x_0, x_1, \dots, x_{n-1} .

Now, we define x_n to be the \mathcal{L} -greatest element of P_{n-1} , and P_n to be P_{n-1} without x_n but with the \mathcal{T} -predecessors of x_n added. We now argue that the sequence x_0, x_1, \dots has order type ω^* in \mathcal{L} .

Clearly all x_i are distinct, since $x_i \notin P_i$ but $x_{i+1} \in P_i$. Suppose that $x_i <_L x_{i+1}$, then $x_{i+1} \notin P_{i-1}$, as otherwise it would have been chosen as x_i , so x_{i+1} must be a \mathcal{T} -predecessor of x_i , and therefore $x_{i+1} <_T x_i$, which is a contradiction of \mathcal{L} being a linear extension of \mathcal{T} . We therefore have $x_{i+1} <_L x_i$ for all i and hence \mathcal{L} is not computably well-founded. \square

The Kleene Tree is a natural example, though it is by no means the only way of constructing an infinite computable binary tree with no computable path, and indeed any such object would suffice to prove the theorem. It should be noted that this counter-example also gives the result for computably enumerable linearisations, because

a computably enumerable linear order with a computable domain, will in fact just be computable. Although Rosenstein did not claim this corollary, it immediately follows from Theorem 2.5.

Corollary 2.6.

There is a computably well-founded computable partial order which does not have a computably well-founded *computably enumerable* linear extension.

Theorem 2.5 is the first negative result, showing that there is a partial order which does not allow preservation of the given property under computable linear extension. This establishes the negative lower bound, and prompts us to look for a positive upper bound. Rosenstein and Statman also gave a positive result, that is they gave an upper bound on the complexity of the computation necessary to obtain a computably well-founded linear extension of a computably well-founded computable partial order.

Theorem 2.7 (Rosenstein and Statman 1984 [43]).

A computably well-founded computable partial order has a computably well-founded Δ_2 linear extension.

Proof. Given some computably well-founded computable partial order \mathcal{P} , we construct a linearisation \mathcal{L} which is computably well-founded. In order for \mathcal{L} to be computably well-founded, it suffices to show that no c.e. set W_e enumerates an infinite descending sequence in \mathcal{L} .

We can ensure this for each W_e in turn if we can ask an oracle if W_e is infinite. If W_e is finite it will clearly not enumerate an infinite descending sequence, but if it is infinite then we may need to construct \mathcal{L} in such a way as to avoid an ω^* -sequence. Of course if W_e is infinite then we will have the opportunity to do this, because since W_e cannot enumerate an ω^* -sequence in \mathcal{P} , it must contain infinitely many \mathcal{P} -incomparable suborderings, which can be enumerated into \mathcal{L} to not build an infinite descending

sequence.

“Is W_e infinite?” is a Π_2 question, but in fact we can use a simpler Σ_1 oracle which answers the question “Does W_e have another element?”, and hence the construction of \mathcal{L} in order to be computably well-founded is computable in a Σ_1 set, or in other words, \mathcal{P} has a Δ_2 linearisation which is computably well-founded. \square

2.2 The upper bound

Downey, in his 1998 survey article on Computability and Linear Orderings [11], asked whether this Δ_2 bound of Rosenstein and Statman could be improved. In Lee’s PhD thesis [29], he presented a result, jointly with Cooper and Morphett, which improves the bound using the Ershov difference hierarchy.

Rosenstein’s argument in the proof of Theorem 2.7 uses a $0'$ oracle, but it is unclear on whether there is a computable bound on the number of times the oracle is queried, i.e. whether the construction is tt-reducible to $0'$ and therefore ω -c.e. (c.f. Theorem 1.4). Cooper, Lee and Morphett re-cast this construction as a full-approximation priority argument, giving an improved bound of ω -c.e.

The proof we give here is a slight modification of the Cooper, Lee and Morphett proof, in particular we use a stronger restraint to make the proof easier to adapt for results in later chapters.

Theorem 2.8 (Cooper, Lee and Morphett 2011 [29]).

A computably well-founded computable partial order has a computably well-founded ω -c.e. linear extension.

Proof. Let $\mathcal{P} = (\mathbb{N}, \leq_P)$ be a computably well-founded computable partial order. We

build a linearisation \mathcal{L} of \mathcal{P} as the limit of a uniformly computable sequence of finite linear orderings $(\mathcal{L}_s = (\mathbb{N}|_s, \leq_{L,s}))_{s \in \omega}$, such that the limit $\lim_{s \rightarrow \infty} \leq_{L,s} = \leq_L$ exists and is a linear extension of \leq_P .

By examining the construction, we shall show there is a computable bound on the number of changes to each element of $\leq_{L,s}$, that is the set of s such that $\leq_{L,s}$ does not agree with $\leq_{L,s+1}$ on given $a, b \in \mathbb{N}$ is bounded by a computable function in a and b (and so in $\langle a, b \rangle$). Hence, the limit $\leq_L = \lim_{s \rightarrow \infty} \leq_{L,s}$ is ω -c.e.

Let W_e be the e -th computably enumerable set, under the standard listing, and let $x_0^e, x_1^e, x_2^e, \dots$ be the elements of W_e in the order they are enumerated. Clearly, if $(y_i)_{i \in \omega}$ is a computable sequence, then there is some e such that $y_i = x_i^e$ for all i .

To ensure that \mathcal{L} is computably well-founded, it suffices to ensure that no sequence $(x_i^e)_{i \in \omega}$ defines an ω^* -sequence in \mathcal{L} . As in the proof of Theorem 2.7 we achieve this for each infinite W_e by finding some $x_i^e, x_{i+1}^e \in W_e$ such that $x_i^e <_P x_{i+1}^e$ or $x_i^e \mid_P x_{i+1}^e$ and $x_i^e >_L x_{i+1}^e$ so we can change the order in the linearisation. Then W_e cannot define an ω^* -sequence as it contains an ascending pair.

If W_e is infinite then such x_i^e, x_{i+1}^e must exist as otherwise W_e would define an ω^* -sequence in \mathcal{P} , contradicting the assumption that \mathcal{P} is computably well-founded.

2.2.1 Requirements

The construction will satisfy the following requirements, for $e \in \omega$,

N : \mathcal{L} is a linear extension of \mathcal{P} .

R_e : W_e does not define an ω^* -sequence in \leq_L .

To satisfy the requirements we place them in a finite injury construction, with the requirements in the priority ordering $N \succ R_0 \succ R_1 \succ R_2 \succ \dots$.

2.2.2 Strategy

We ensure that \mathcal{L} is a linear extension of \mathcal{P} by defining at every stage \mathcal{L}_s to be a linear extension of $\mathcal{P} \upharpoonright_s$. Then to ensure that the limit $\lim_{s \rightarrow \infty} \mathcal{L}_s$ exists, we restrain the requirement R_e from acting on $\leq_{L,s} \upharpoonright_e$. So only finitely many requirements can modify any part of $\leq_{L,s}$, and since we will show each requirement can only act finitely often, the limit exists. This also gives a computable bound on the number of changes, and hence that the ordering \leq_L is ω -c.e.

For each requirement R_e , we set a restraint threshold $t_e[s]$, which is the \mathbb{N} -greatest number which R_e needs preserved from future alteration in order to ensure it remains satisfied, at the beginning of stage s . We also define $T_e[s] = \{n \in \mathbb{N} \mid n \leq_{\mathbb{N}} \max\{t_{e'}[s] \mid e' < e\}\}$, which is the portion of $\leq_{L,s}$ which R_e is not permitted to alter, in order to avoid injuring higher priority requirements.

To satisfy R_e , we look for elements $x_i^e, x_{i+1}^e \geq_{\mathbb{N}} e$, such that either they are \leq_P -comparable and $x_i^e <_P x_{i+1}^e$ or they are \leq_P -incomparable and such that we can make them an ascending pair in \mathcal{L} without affecting $\leq_{L,s+1}$ on $T_e[s]$, and therefore without injuring the restraint of any higher priority requirement, in particular such that there is no element of $T_e[s]$ between them. We will argue that if W_e is infinite, then we will eventually find some suitable pair of elements.

In the first case, if we find a pair of elements which prevent W_e from enumerating an infinite descending chain, then we say that R_e has been discharged, and move on.

In the second case, we plummet the element x_i^e , called the *plummet witness*, $\leq_{L,s}$ -below x_{i+1}^e as follows. Suppose that $x_{i+1}^e = c_k \leq_{L,s-1} \cdots \leq_{L,s-1} c_1$ is a list in \mathcal{L}_{s-1} of the finite set

$$\{c \mid c \in \mathcal{L}_{s-1} \text{ and } x_j^e \leq_{L,s-1} c <_{L,s-1} x_i^e \text{ and } c \not\leq_P x_i^e\}$$

and notice that clearly $c_n \upharpoonright_P x_i^e$ for all c_n (and therefore c_n is also \leq_P -incomparable with any element \leq_P -comparable to x_i^e), since $\leq_{L,s-1}$ extends \leq_P on the elements already enumerated.

Now, for any $c_1 \leq_{L,s-1} d \leq_{L,s-1} x_i^e$, we must have that $d \leq_P x_i^e$ but by definition $c_1 \not\leq_P x_i^e$ and therefore $c_1 \not\leq_P d$. Hence, c_1 can be moved past d . Denote by $x_i^e + 1$ the immediate successor of x_i^e in \mathcal{L}_{s-1} if it exists and move c_1 until $x_i^e \leq_{L,s} c_1 \leq_{L,s} x_i^e + 1$. Then by the same argument, we can repeat the process for all c_i to get $x_i^e \leq_{L,s} c_k \leq_{L,s} \cdots \leq_{L,s} c_1 \leq_{L,s} x_i^e + 1$. If the successor $x_i^e + 1$ does not exist then just move c_1 to immediately above x_i^e and then proceed as if $c_1 = x_i^e + 1$.

Notice that since $x_j^e \leq_{L,s-1} x_i^e$ at stage $s - 1$ and $x_j^e \in \{c_1, \dots, c_k\}$, at the end of stage s we have $x_i^e \leq_{L,s} x_j^e$, and hence $W_{e,s}$ is not a descending sequence. Now set $t_e[s + 1] = \max\{x_i^e, x_{i+1}^e\}$. After we have completed the plummeting, we say that R_e is discharged.

2.2.3 Construction

At stage 0, set $t_e[0] = 0$ for all e .

At stage $2s + 1$ we enumerate the number s into \mathcal{L}_s , as high as possible whilst ensuring that \mathcal{L}_{2s+1} is a linear extension of $\mathcal{P} \upharpoonright_s$, and so the transitive closure of $\mathcal{L}_{2s+1} \cup \mathcal{P}$ is a partial order, because of the “high as possible” constraint.

We say that R_e *requires attention* at stage s if the elements of $W_{e,s}$ describe the start of an ω^* -sequence in \leq_L , and R_e can be satisfied at stage s , i.e. there are two elements $x_i^e, x_{i+1}^e >_{\mathbb{N}} T_e[s]$ which are \leq_P -incomparable, greater than e and there is no $n \leq T_e[s]$ between x_i^e and x_{i+1}^e in $\mathcal{L}[s]$.

At stage $2s + 2$ we find the least e such that R_e requires attention (if no such e exists then end the stage and go on to stage $2s + 3$). Then take the elements x_i^e, x_{i+1}^e as described above and plummet the element $x_i^e \leq_{L,2s+2}$ -below x_{i+1}^e by defining $x_i^e \leq_{L,2s+2} x_{i+1}^e$ as described above. Set $t_e[2s + 1] = \max\{x_i^e, x_{i+1}^e\}$ and $t_{e'}[2s + 2] = 0$ for all $e' >_{\mathbb{N}} e$. This ensures that W_e does not define an ω^* -sequence, because it contains at least one ascending pair x_i^e, x_{i+1}^e , but \mathcal{L}_{2s+2} is still a linear extension of $\mathcal{P} \upharpoonright_s$.

2.2.4 Verification

Lemma 2.9.

\mathcal{L} is a linear extension of \mathcal{P} .

Proof. At every stage \mathcal{L}_s is defined to be a linear extension of $\mathcal{P} \upharpoonright_s$, and any finite initial segment of the linearisation is fixed after a finite number of stages, so the limit $\lim_{s \rightarrow \infty} \mathcal{L}_s = \mathcal{L}$ exists, and is a linear extension of \mathcal{P} . \square

Lemma 2.10.

\mathcal{L} is computably well-founded.

Proof. If \mathcal{L} were not computably well-founded then there would be some computable subchain of \mathcal{L} which had order type ω^* . And so there would be some computably enumerable set W_e which enumerated this subchain as an ω^* -sequence, and so the requirement R_e would not be satisfied.

Let s_0 be a stage such that $T_e[s]$ is fixed for all $s \geq s_0$, which exists because the requirements with higher priority can only act a finite number of times. We can show this by induction on e . Obviously R_0 only acts at most once, so we have the base case, then assuming for induction that the requirements $R_{e'}$ for $e' < e$ act finitely often, we see that R_e must act at most once more than the combined number of actions of all $R_{e'}$, which will also be finite. Hence, s_0 exists. We now argue that R_e is satisfied after s_0 .

We suppose that W_e is infinite, because if W_e is finite then R_e is trivially satisfied. If the finite part of W_e which has been enumerated by stage s_0 does not define a descending sequence, then R_e will be satisfied, so suppose it does. Then if R_e is never satisfied, the enumeration of W_e after stage s_0 must go on to define a ω^* -sequence, and never require attention, because if it did then R_e would act to satisfy itself with highest priority, since all requirements of higher priority are satisfied by stage s_0 . Therefore it must be the case that there is no pair $x_i^e, x_{i+1}^e \geq_{\mathbb{N}} T_e[s_0]$ which is incomparable in \mathcal{P} , greater than e and such that there is no $n \leq_{\mathbb{N}} T_e[s_0]$ between x_i^e and x_{i+1}^e in $\mathcal{L}[s_0]$.

$T_e[s_0]$ is finite, and so then there will an \leq_L -least element and since W_e is infinite and descending there will be an infinite subset of W_e which is \leq_L -below all elements of $T_e[s_0]$. This infinite subset then defines a computable ω^* -sequence in \mathcal{P} , which contradicts the fact that \mathcal{P} is computably well-founded.

Hence, all requirements R_e are satisfied and \mathcal{L} is computably well-founded. □

Lemma 2.11.

\mathcal{L} is ω -c.e.

Proof. If R_e acts at stage s , it will remain satisfied and will not act again at a subsequent stages, unless it is injured by a requirement with higher priority. Hence, any requirement

will act at most 2^e times. Since R_e cannot make changes to $\leq_{L,s}$ for numbers $\leq e$, $\leq_{B,s} \upharpoonright_e$ can change at most $2^e - 1$ times, and so changes in \leq_L are computably bounded, and \mathcal{L} is ω -c.e. □

This completes the proof of Theorem 2.8. □

2.3 Computable extendibility

We now consider extendibility from a computable point of view, beginning by defining the appropriate notions of computable extendibility.

Definition 2.12.

A computable order type α is *computably extendible* if any computable partial order \mathcal{P} which does not computably embed α can be extended to a computable linear order \mathcal{L} which does not computably embed α .

A computable order type α is *computably 2-c.e.-extendible* (resp. Δ_2 -extendible, ω -c.e.-extendible, n -c.e.-extendible) if any computable partial order \mathcal{P} which does not computably embed α can be extended to a 2-c.e. (resp. Δ_2 , ω -c.e., n -c.e.) linear order \mathcal{L} which does not computably embed α .

Theorems 2.5, 2.7 and 2.8 above can now be re-stated more concisely using this terminology.

Theorem 2.13.

- ω^* is not computably extendible. [Rosenstein and Statman 1984 [43]]
- ω^* is computably Δ_2 -extendible. [Rosenstein and Statman 1984 [43]]
- ω^* is computably ω -c.e.-extendible. [Cooper, Lee and Morphett 2011 [29]]

2.4 The lower bound

We now show that Cooper, Lee and Morphett's result is in fact the best possible, and the bound cannot be lowered to n -c.e. for any finite n , because we can exhibit a counterexample, for any given n of a computably well-founded computable partial order, which cannot be extended to a computably well-founded n -c.e. linear extension. We will initially prove this in the case of $n = 2$ (note that the case $n = 1$ is just Corollary 2.6) and then show how to generalise that case to any n .

Theorem 2.14.

There exists a computably well-founded computable partial order \mathcal{P} which has no computably well-founded 2-c.e. linear extension. That is, ω^* is not computably 2-c.e.-extendible.

Proof. We construct as a witness a computable partial order $\mathcal{P} = (\mathbb{N}, \leq_P)$ as the disjoint union of sub-partial orderings $\mathcal{P}_e = (P_e, \leq_P \upharpoonright P_e)$ such that each \mathcal{P}_e forms a connected component of \mathcal{P} , and in particular every element of \mathcal{P}_e is incomparable to every element of every other \mathcal{P}_f where $e \neq f$. We will assume a computable listing of 2-c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, where $R_{\langle i, j \rangle} = W_i \setminus W_j$, and an associated computable approximation $R_{\langle i, j \rangle}[s] = W_i[s] \setminus W_j[s]$. Then the purpose of \mathcal{P}_e is to show that if R_e is a linearisation of \leq_P , then there exists a computable ω^* -sequence in R_e . By construction, such a sequence will be made up of elements of P_e .

We will construct \mathcal{P}_e in such a way that any ω^* -sequence in \mathcal{P}_e computes the halting set K , and is therefore not computable. Since there are no \leq_P -comparabilities between the components and each component is computably well-founded, we have that \mathcal{P} as a whole is computably well-founded.

At each stage s of the construction we define an approximation $\mathcal{P}[s]$ with domain

some finite initial segment of \mathbb{N} , we also compute the approximations $R_e[s]$ for $e < s$ and an approximation $K[s]$ of the halting set, to be used in the construction. At stage 0, $P[0] = \emptyset$, then at stage $s + 1$ we add up to four new elements to each $\mathcal{P}_e[s]$ with $e < s$ and four new elements to $\mathcal{P}_s[s]$. When a number n enters the construction at a stage s , all of the \leq_P -comparabilities of n with $k < n$ are set at stage s and do not change at any later stage. So each \mathcal{P}_e is computable because if we wish to compute \leq_P relative to a pair of numbers (n, m) then it suffices to run the construction until stage $s = \max\{n, m\} + 1$ and the approximation to \leq_P relative to (n, m) at stage s will be the true value, and hence \mathcal{P} is computable.

We now fix some $e \in \mathbb{N}$ and consider the construction of \mathcal{P}_e . At all stages $s \leq e$, $\mathcal{P}_e[s] = \emptyset$, then at stage $s = e + 1$, four new elements are added to define $\mathcal{P}_e[s + 1]$, with the comparabilities $b_{-1} <_P y <_P a_{-1}$ and $b_{-1} <_P x <_P a_{-1}$ as shown in Figure 2.2. We define (b_{-1}, a_{-1}) to be the *Level 1 active interval* and also to be the *Level 2 active interval*.

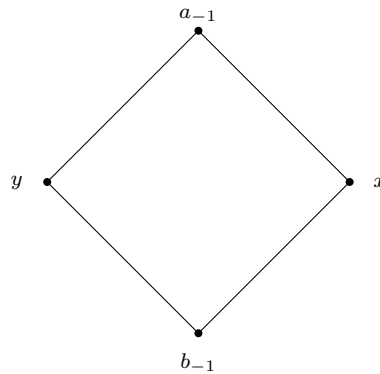


Figure 2.2: The first four elements of \mathcal{P}_e , added at stage $e + 1$

The labels y and x are temporary and will be reused many times during the construction for different elements before they are given a permanent label.

Definition 2.15.

We call a stage $s > e + 1$ a *good stage for e* if $R_e[s]$ linearises $\mathcal{P}_e[s]$. The construction of \mathcal{P}_e will only proceed at good stages for e . Note that the set of good stages for e is computable.

Definition 2.16.

If s is a good stage for e , then for $m, n \in P_e[s]$ we say that $m R_e n$ is *computed at stage s* if $\langle m, n \rangle \in R_e[s]$. Since s is good for e and $R_e[s]$ is therefore a linear order, this obviously means that $\langle n, m \rangle \notin R_e[s]$.

Definition 2.17.

- We say that $m R_e n$ is *1-computed at stage s* if it is computed at stage s and there is no earlier good stage at which $n R_e m$ is computed.
- We say that $m R_e n$ is *2-computed at stage s* if it is computed at stage s and there is an earlier good stage at which $n R_e m$ is 1-computed.

Note that for a pair $m, n \in P_e$, $n R_e m$ can only be computed at a good stage for e , so from now on when we say that $m R_e n$ is computed (or 1-computed, 2-computed, etc) at stage s we mean by definition that s is a good stage for e .

For some R_e it may be the case that $m R_e n$ is 1-computed at stage s and there has been an earlier stage $t < s$ such that $\langle n, m \rangle \in R_e[t]$, and it may even be the case that $\langle m, n \rangle \in R_e[t]$ as well. However, this just means that by definition t is not a good stage for e , and hence neither $m R_e n$ or $n R_e m$ was computed at stage t .

We now consider the simple case in which there is no stage s and pair $k, l \in P_e$ such that $k R_e l$ is 2-computed at stage s . In effect we are initially proving the case for $n = 1$, which is a reproof of Corollary 2.6. We will then consider the case where there

are 2-computed pairs, and show how the construction nests.

Now, suppose that s is the first good stage for e , and without loss of generality suppose that $y R_e x$ is 1-computed at stage s . Then relabel x as b_0 and y as c_0 , and we add four new elements a_0, d_0, y, x into $\mathcal{P}_e[s + 1]$ such that $b_0 <_P y <_P a_0 <_P a_{-1}$, $b_0 <_P x <_P a_0 <_P a_{-1}$ and $b_{-1} <_P d_0 <_P c_0$, as shown in Figure 2.3. and we define the Level 1 active interval to be (b_0, a_0) .

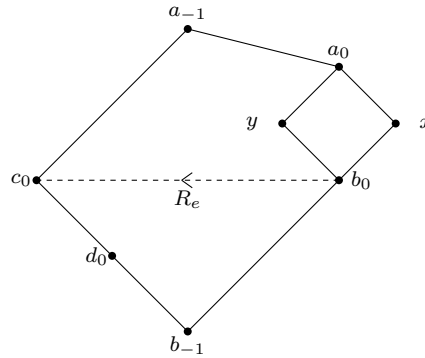


Figure 2.3: After the first good stage for e

At subsequent stages s , the construction will continue in the interval (b_0, a_0) for as long as $0 \notin K[s]$. However, if at stage s , $0 \in K[s]$ then (d_0, c_0) will become the Level 1 active interval and the construction will restart there.

If we assume that $0 \notin K[s]$ for the time being, then at the next good stage s' , if without loss of generality $m_0 R_e n_0$ is 1-computed at stage s' then relabel n_0 as b_1 and m_0 as c_1 , and we add four new elements a_1, d_1, y, x into $\mathcal{P}_e[s' + 1]$ such that $b_1 <_P y <_P a_1 <_P a_0$, $b_1 <_P x <_P a_1 <_P a_0$ and $b_0 <_P d_1 <_P c_1$, as shown in Figure 2.4, and we define the Level 1 active interval to be (b_1, a_1) .

We will then continue the construction in the same way at the subsequent good

stages for e in the interval (b_1, a_1) , unless 1 is enumerated into K , at which time the construction will move to the interval (d_1, c_1) , and we will define that as the new Level 1 active interval, or if 0 is enumerated into K in which case the construction moves to (d_0, c_0) as mentioned above.

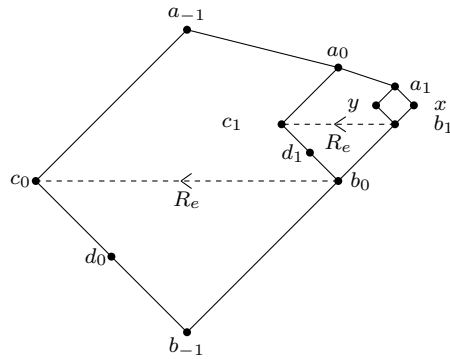


Figure 2.4: After the second good stage for e

Definition 2.18.

When the elements a_i are added we say they are *active*, and we say that a_0 is 0-coloured, a_1 is 1-coloured etc., referring to the number they are testing for membership in K . If i is enumerated into K , then the construction interval will move and all of the j -coloured elements, for $j > i$ will be deactivated, and new j -coloured elements will be defined as the construction continues.

During the construction there may be up to 2^i indices n at each Level of the construction such that a_n is i -coloured, but at a given stage s there is at most one n at each Level such that a_n is i -coloured and active, for each number i .

If i is enumerated into $K[s]$, and there is some $a_n \in P_e[s]$ which is i -coloured and active, then the Level 1 active interval will change, as mentioned above, and any a_m which are j -coloured, for $j > i$, will no longer be in the Level 1 active interval and are said to

become inactive.

So for example if 0 is enumerated into K then any a_n , $n \geq 1$ which have been defined will all be deactivated, the construction moves to the interval (d_0, c_0) and restarts with a new a_{n+1} which is active and 1-coloured.

When the Level 1 active interval is redefined due to a number being enumerated into $K[s]$, we add two new elements to the new Level 1 active interval (d_{i+1}, c_{i+1}) and $<_P$ -incomparable to each other, and call them y and x ¹.

Then at the next good stage t for e , if without loss of generality $y R_e x$ is 1-computed at stage t then relabel x as b_{n+1} and y as c_{n+1} , where $n + 1$ is the least index for which $a_{n+1}, b_{n+1}, c_{n+1}$ have not been defined, and we add four new elements a_{n+1}, d_{n+1}, y, x into $\mathcal{P}_e[t + 1]$ such that $b_{n+1} <_P y <_P a_{n+1} <_P c_{i+1}$ and $b_{n+1} <_P x <_P a_{n+1} <_P c_{i+1}$ and $d_{i+1} <_P d_{n+1} <_P c_{n+1}$, as shown in Figure 2.5, and we define the Level 1 active interval to be (b_{n+1}, a_{n+1}) . Note that a_{n+1} is active with colour $j + 1$, where j is the number which was enumerated into K and caused the Level 1 active interval to be redefined.

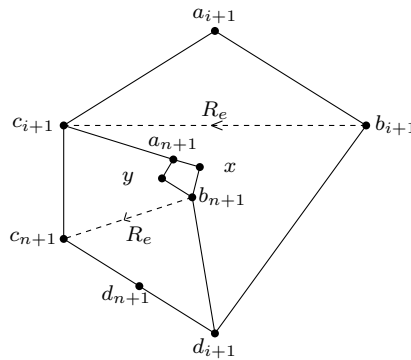


Figure 2.5: After a general good stage for e

¹If there are already numbers in the construction labelled y and x then we can ignore them as they are no longer relevant to the construction.

The construction in the case where no pair is 2-computed is then a simple nesting of the above process. It should be noted that the sequence of a_n defined will be such that $a_{n+1} R_e a_n$ for all n , i.e. they form a descending sequence in R_e , and that if a_n is active and has colour k , then the Level 1 active interval will be within (or all of) either (b_n, a_n) or (d_n, c_n) .

In particular, if the Level 1 active interval lies within (b_n, a_n) and k is seen to be in K , then the Level 1 active interval will be redefined to be (d_n, c_n) , and any a_p which have been defined for $p > n$ will be deactivated. Although given the nested nature of the construction, some of those may have already been deactivated at an earlier stage.

If there are only finitely many good stages, then \mathcal{P}_e will be finite, and the necessary conditions for the theorem trivially hold, as it contains no ω^* -sequence, and R_e is not a linearisation of \mathcal{P}_e . Indeed if R_e is a linearisation of \mathcal{P}_e then there will be infinitely many good stages for e , at each of which either two or four elements were added to \mathcal{P}_e , and hence \mathcal{P}_e would be infinite.

If \mathcal{P}_e is infinite, still under the supposition that there is no pair which is ever 2-computed, then the a_n form an infinite descending sequence in R_e , and for each $i \in \mathbb{N}$ there is exactly one a_n which is i -coloured and active at all good stages for e after some finite stage s_i . We call this the test witness for i .

Suppose then that there is some ω^* sequence $\{x_n\}_{n \in \mathbb{N}}$ in \mathcal{P}_e . If there is any k such that $b_0 <_P x_k$ then $0 \notin K$ and if there is any k such that $x_k <_P c_0$ then $0 \in K$. Only one of these can be true, since $b_0 <_P y$ and $z <_P c_0$ implies that $y|_P z$, but all x_n must be $<_P$ -comparable, and since elements are only put in the intervals (b_0, a_0) and (d_0, c_0) . Therefore, if we know the location of the sequence (or in fact any element of the sequence), relative to b_0 and c_0 , we know whether $0 \in K$ or $0 \notin K$.

Then by simulating the construction above, we can find the test witness for 1, and depending on where we can find an element of $\{x_n\}_{n \in \mathbb{N}}$, compute whether $1 \in K$. And so on for any number i we can use the position of the x_n to compute whether $i \in K$ and hence there is an algorithm defined uniformly in e which computes K with oracle $\{x_n\}_{n \in \mathbb{N}}$. So any ω^* sequence $\{x_n\}_{n \in \mathbb{N}}$ in \mathcal{P}_e computes K and hence \mathcal{P}_e is computably well-founded.

If R_e linearises \mathcal{P}_e , then we can find a computable ω^* -sequence in R_e . In fact by construction, $\{a_n\}_{n \in \mathbb{N}}$ is a computable descending sequence in R_e , which will be infinite as we know that R_e linearising \mathcal{P}_e means that \mathcal{P}_e will be infinite, and therefore R_e is not computably well-founded. This concludes the proof of the simpler case in which there is no pair which is ever 2-computed.

Now, suppose that in fact there is at least one pair $n, m \in P_e$ such that $n R_e m$ is 2-computed at some stage s . Note that without loss of generality we can in fact assume that the 2-computed pair is c_n, b_n for some n , because if any pair is 2-computed then there will be some c_n, b_n that is 2-computed, by inspection of the construction. Thus during the construction below we only need to search for the least index k such that $b_k R_e c_k$ is 2-computed at stage $s + 1$.

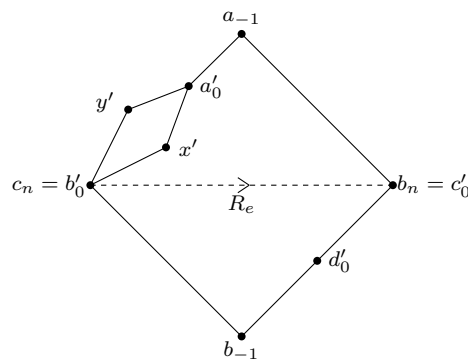


Figure 2.6: After the first stage at which a pair is 2-computed

So, suppose we are at the first stage at which some c_n, b_n is 2-computed, and suppose that n is the least index of a 2-computed pair. Then we relabel c_n as b'_0 , b_n as c'_0 and add four new numbers a'_0, d'_0, y', x' to $P_e[s + 1]$ such that $b'_0 <_P y' <_P a'_0 <_P a_{-1}$, $b'_0 <_P x' <_P a'_0 <_P a_{-1}$ and $b_{-1} <_P d'_0 <_P c'_0$, as shown in Figure 2.6. Then we define (b'_0, a'_0) to be the Level 1 active interval and also the Level 2 active interval.

It is important to note here that a'_0 is active and 0-coloured, and all previous active elements have been deactivated at this stage. So if at some stage $s' > s$ we have that $0 \in K[s']$, then both the Level 1 active interval and the Level 2 active interval will move to (d'_0, c'_0) .

The Level 1 construction then restarts from scratch in the new Level 1 interval, building a new a_n sequence until such a time as there is another stage t at which some pair is 2-computed. Assuming that m is the least index of such a 2-computed pair b_m, c_m , we redefine b_m as c'_1 and c_m as b'_1 and add a'_1, d'_1, x', y' such that $b'_1 <_P y' <_P a'_1 <_P a'_0$, $b'_1 <_P x' <_P a'_1 <_P a'_0$ and $b'_0 <_P d'_1 <_P c'_1$ as shown in Figure 2.7. (Assuming that $0 \notin K[s - 1]$, if $0 \in K[s - 1]$ then replace a'_0, b'_0 by d'_0, c'_0 respectively.)

The Level 2 active interval is now redefined to be (b'_1, a'_1) , and a'_1 is 1-coloured and active.

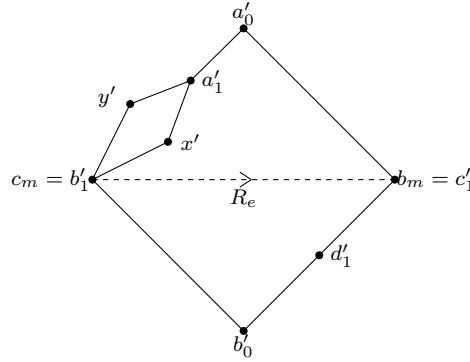


Figure 2.7: After the second stage at which a pair is 2-computed

It should be noted here that a'_1 is directly below a'_0 , and not below any other elements which may have been added at stages between s and t . Those elements are now irrelevant, and incomparable to the rest of the construction. Any coloured elements apart from a'_0 and a'_1 are deactivated.

Then the Level 1 construction restarts as before in the new Level 1 active interval (b'_1, a'_1) (or (d'_1, c'_1) if $1 \in K[t+1]$). We see that if there are only finitely many stages at which the Level 2 active interval is redefined, then from some stage s all activity in the construction will be at Level 1, and we get the same outcomes as in the first case. Namely, if R_e is a linearisation of \mathcal{P}_e , then it contains a computable ω^* -sequence $\{a_n\}_{n \in \mathbb{N}}$ in the eventually permanently active Level 2 interval. And any ω^* -sequence in \mathcal{P}_e will compute K , by performing the same analysis as earlier but within the eventually permanently active Level 2 interval, since we know that the construction outside of that interval will be finite and hence there will be an infinite part of any ω^* -sequence within the interval. So as before we compute K by performing tests relative to the relevant (b_n, c_n) pairs in the interval to determine if $k \in K$ for any $k \in \mathbb{N}$.

Alternatively the Level 2 active interval may be redefined infinitely many times, or

in other words there may be infinitely many stages at which there is a 2-computed pair. In this case, if R_e is a linearisation of \mathcal{P}_e , then the sequence $\{a'_n\}_{n \in \mathbb{N}}$ is a computable ω^* -sequence in R_e and we still have that any ω^* -sequence in \mathcal{P}_e is not computable, because we can again use the location of (any element of) the sequence relative to the b'_i, c'_i pairs to compute K .

To show that $\{a'_n\}_{n \in \mathbb{N}}$ is a computable sequence, notice that the pairs (b'_n, c'_n) which are 2-computed, can be found by a uniformly computable search, and hence there is an algorithm which computes the sequence of such pairs in order, and therefore also computes a'_0, a'_1, a'_2, \dots

To show that any ω^* -sequence in \mathcal{P}_e computes K , let $\{x_n\}_{n \in \mathbb{N}}$ be such a sequence, then in the same way as we computed K in the earlier case, we can compute K in this case by using the b'_n and c'_n , which are computable as discussed above, and simulating the construction to perform tests in the same manner as before but at the higher level.

Since e was arbitrary, we see that \mathcal{P} has no computably well-founded 2-c.e. linear extension, and any infinite descending sequence in \mathcal{P} computes K and hence \mathcal{P} is computably well-founded. But we have also seen that the construction of \mathcal{P} is entirely computable. This concludes the proof of Theorem 2.14. \square

This construction is significantly more complex than the Kleene Tree counterexample of Theorem 2.5. The Kleene Tree is a nice natural example, but cannot be used in this case because it is possible to construct a 2-c.e. linearisation of the Kleene Tree which has no computable infinite descending sequence. This can be done using the method of diagonalising against the c.e. sets and plummeting elements, similarly to the proof of Theorem 2.8.

We now show how to generalise this proof to give a construction of computably well-founded computable partial order which has no computably well-founded n -c.e. linear extension, for any given $n \in \mathbb{N}$.

Corollary 2.19.

For every $n \geq 1$, there exists a computably well-founded computable partial order \mathcal{P} which has no computably well-founded n -c.e. linear extension. That is, ω^* is not computably n -c.e.-extendible, for any $n \in \mathbb{N}$.

Proof. A computably enumerable 1-c.e. linearisation of \mathcal{P} will be computable. We proved the $n = 1$ case as the first part of the proof for $n = 2$, and of course the Kleene Tree constructed by Rosenstein and Statman as a witness to Theorem 2.5 also proves this case. We now show how to generalise the proof of the $n = 2$ case above to any $n \in \mathbb{N}$.

Consider the $n = 3$ case. We perform the construction as with $n = 2$, but with an extra layer. The construction can now define Level 3 active intervals. When a Level 3 active interval is defined or redefined all Level 2 and Level 1 construction is restarted from scratch in the new Level 3 interval. At Level 3 we will be building a computable sequence a''_n , descending in R_e , when pairs b''_n, c''_n are 3-computed.

We will assume a computable listing of 3-c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, where $R_{\langle i,j,k \rangle} = (W_i \setminus W_j) \cup W_k$, and an associated computable approximation $R_{\langle i,j,k \rangle}[s] = (W_i[s] \setminus W_j[s]) \cup W_k[s]$.

We define 3-computation in the obvious way. We say that $m R_e n$ is *3-computed at stage s* if it is computed at stage s and there is an earlier good stage at which $n R_e m$ is 2-computed. And in general, if R_e is a k -c.e. set, then we say that $m R_e n$ is *r -computed at stage s* , for some $r \leq k$, if it is computed at stage s and $r = 1$ or $r > 1$ and there is an earlier good stage at which $n R_e m$ is $r - 1$ -computed and there is no good stage $\leq s$ at which $n R_e m$ is $r + 1$ -computed.

The construction in the case where there is 3-computation works in the same way relative to 2-computation as 2-computation works relative to 1-computation. For example when the first pair is 3-computed this is because a 2-computed pair (b'_n, c'_n) has been found such that $b'_n R_e c'_n$ is 3-computed at this stage s (and n is the least index of such a pair). So we enumerate new elements a''_0, d''_0, x, y and redefine $b''_0 = c'_n$ and $c''_0 = b'_n$, as shown in Figure 2.7.

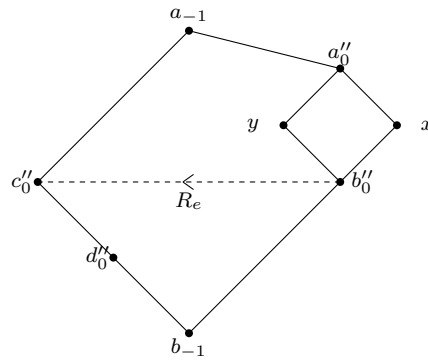


Figure 2.8: After the first pair is 3-computed

Then the construction at Level 2 and Level 1 restarts from scratch in the new Level 3, 2 and 1 active interval (b''_0, a''_0) . It behaves as a nested version of the construction in the Theorem above, but with the difference that the Level 3 active interval can be redefined either finitely or infinitely often.

We take the greatest $t \in \{1, 2, 3\}$ such that the Level t active interval is redefined infinitely often. If the Level 3 active interval is redefined infinitely often then if R_e linearises \mathcal{P}_e then the a''_n form a computable infinite descending chain in R_e , and if $\{x_n\}_{n \in \mathbb{N}}$ is an ω^* -sequence in \mathcal{P}_e then it computes K . If it is redefined only finitely often, then after some finite stage it will be fixed, and the remainder of the construction will be at Level 2 and Level 1. So the outcomes are the same as in the $n = 2$ case.

The case for n -c.e. is then a straightforward generalisation of this; take a computable listing of n -c.e. sets R_e and associated approximations $R_e[s]$, and define n -computation as above. Work through the construction as in the $n - 1$ case, but when something is n -computed we define the points $a_i^{(n-1)}, b_i^{(n-1)}, c_i^{(n-1)}, d_i^{(n-1)}$ and redefine the Level n active interval. If R_e linearises \mathcal{P} then will then be some $1 \leq t \leq n$ such that the Level t active interval is redefined infinitely often. Then is t is the greatest of those, if R_e linearises \mathcal{P}_e then the $\{a_n^{(t-1)}\}_{n \in \mathbb{N}}$ will be a computable ω^* -sequence in R_e .

However, any ω^* -sequence in \mathcal{P}_e will compute K in the same way as discussed above, since the construction at the t level is computable and so we can use the position of the sequence relative to the $\{a_n^{t-1}\}_{n \in \mathbb{N}}$ to determine membership of elements of K .

Then for any n we can construct a witness \mathcal{P} which is computable and computably well-founded, but has no computably well-founded n -c.e. linearisation. \square

It is interesting to note the reasons why this construction fails for ω -c.e., which is because if there is no fixed bound on the number of times a pair can be changed in the linearisation, then there will not necessarily be a greatest t such that the Level t active interval is redefined infinitely often. In fact we could have no such t and just keep redefining intervals of greater and greater Level, but only finitely often. Thus we cannot build the computable ω^* -sequence necessary in R_e and the argument fails.

Whilst in the proof of this theorem, we construct a separate counterexample for each $n \geq 1$, it is in fact possible to build one witness which proves the theorem for all $n \geq 1$. To do this, we need a listing of all n -c.e. sets, for all $n \geq 1$, which we define $\{R_{\langle n,e \rangle}\}_{n,e \in \mathbb{N}}$ with uniform approximations $\{R_{\langle n,e \rangle}[s]\}_{n,e,s \in \mathbb{N}}$.

Let $g : \mathbb{N}^3 \rightarrow \mathbb{N}$ be a computable function such that

$$W_{g(n,e,k)} = \begin{cases} \bigcap_{0 \leq i \leq k} W_{e_i} & \text{if } 0 \leq k \leq n \text{ (where } e = \langle e_0, e_1, \dots, e_{n-1} \rangle), \\ \emptyset & \text{if } k > n. \end{cases}$$

Note that n determines the length of the tuple coded as e , and if $n = 0$ then we use the convention that $e = \langle e \rangle$, so $e_0 = e$.

Then

$$R_{\langle n,e \rangle} = \bigcup_{i=0}^{\lfloor \frac{n}{2} \rfloor} W_{g(n,e,2i)} \setminus W_{g(n,e,2i+1)},$$

and $R_{\langle n,e \rangle}[s]$ is defined using the stage s approximations to all the of c.e. sets involved.

The construction then proceeds in the usual way, with $\mathcal{P}_{\langle e,n \rangle}$ being the component of the witness which shows that if $R_{\langle e,n \rangle}$ is a linearisation of \mathcal{P} then there exists a computable ω^* -sequence in $R_{\langle e,n \rangle}$. Notice that because n is encoded in the index of $\mathcal{P}_{\langle e,n \rangle}$, we can computably determine which algorithms from the above proofs to use in the construction, and hence the construction remains computable. In effect we simultaneously perform the constructions for the proof for each $n \geq 1$.

Chapter 3

The order type ζ

The order type of the integers $\zeta = \omega^* + \omega$ is another key order type, which we will investigate the extendibility of in this chapter. Unlike the order types considered in Chapters 2 and 4, there have not been any bounds previously established on the complexity of linearisations which do not computably embed ζ of computable partial orders which do not computably embed ζ . So in this chapter we will establish such bounds from scratch.

3.1 Background

We do have the starting point that ζ is classically extendible, by a theorem of Jullien [21] and independently of Galvin and McKenzie (unpublished).

Theorem 3.1 (Jullien 1969 [21]).

The order type ζ is extendible.

Proof. Let \mathcal{P} be a partial order that does not embed ζ . Define $I = \{x \in P \mid \omega^* \text{ does not embed in } \mathcal{P}(x)\}$ and $F = \{x \in P \mid \omega \text{ does not embed in } \mathcal{P}^*(x)\}$, where

$\mathcal{P}(x) = \{y \in P \mid y \leq_P x\}$ and $\mathcal{P}^*(x) = \{y \in P \mid y \geq_P x\}$. Then clearly $I \cup F = P$.

Obviously ω^* does not embed in I and ω does not embed in F , and so there are linear extensions $\mathcal{L}(I)$ and $\mathcal{L}(F)$ such that ω^* does not embed in $\mathcal{L}(I)$ and ω does not embed in $\mathcal{L}(F)$, since ω^* is extendible by Theorem 2.2, and the dual of an extendible type obviously also being extendible. Then the lexicographic sum $\mathcal{L}(I) + \mathcal{L}(F) \upharpoonright_{P \setminus I}$ is a linear extension of \mathcal{P} which does not embed $\omega^* + \omega$. \square

The effective content of this theorem has not been discussed in the literature. Given the other results in this Chapter, whilst parallels can in some cases be drawn from the well-founded case, we see that this is not necessarily always so. Hence we do not conjecture about the result for computable orderings, but note that it is an open question.

Open Question 3.2.

Does every computable partial order which does not embed ζ have a computable linearisation which does not embed ζ ?

In Theorem 2.5, Rosenstein and Statman used a Kleene Tree as a witness of a computably well-founded computable partial order with no computably well-founded computable linearisation. Or in other words, that ω^* is not computably extendible. We can use a similar witness here as a counterexample to the computable extendibility of ζ .

Theorem 3.3.

The order type ζ is not computably extendible.

Proof. We build a partial order \mathcal{P} as a copy of the Kleene Tree $KT \leq_P$ -below the dual of the Kleene Tree KT^* to witness the theorem. Then if this partial order contains a computable suborder of the type $\omega^* + \omega$, we must have that KT contains a computable ω^* -sequence and KT^* contains a computable ω -sequence. But by construction that cannot happen, so we know that \mathcal{P} cannot computably embed $\omega^* + \omega$.

If \mathcal{L} is a computable linearisation of \mathcal{P} then it consists of the order sum of a computable linearisation of KT and a computable linearisation of KT^* . We know that any computable linearisation of KT must contain a computable ω^* -sequence, and similarly any computable linearisation of KT^* must contain a computable ω -sequence, so \mathcal{L} contains a computable $\omega^* + \omega$ -sequence as required. \square

As before, this result immediately gives the same theorem for computably enumerable linearisations, because a computably enumerable linear order with a computable domain is computable. Thus this corollary follows directly from Theorem 3.3.

Corollary 3.4.

The order type ζ is not computably c.e.-extendible.

3.2 The lower bound

We can improve the lower bound from c.e. (Corollary 3.4) to n -c.e. for any $n \geq 1$, by combining the structure of the proof of Theorem 2.14 with the idea of the counterexample in the proof of Theorem 3.3.

Theorem 3.5.

The order type ζ is not n -c.e. extendible for any $n \geq 1$.

Proof. In the same way as before, we will demonstrate that ζ is not computably 2-c.e. extendible, and then generalise to all n .

For the $n = 2$ case, we construct as a witness a computable partial order $\mathcal{P} = (\mathbb{N}, \leq_P)$ as the disjoint union of sub-partial orderings \mathcal{P}_e such that each \mathcal{P}_e forms a connected component of \mathcal{P} , and in particular every element of \mathcal{P}_e is incomparable to every

element of every other \mathcal{P}_f where $e \neq f$. We will assume a computable listing of 2-c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, where $R_{\langle i,j \rangle} = W_i \setminus W_j$, and an associated computable approximation $R_{\langle i,j \rangle}[s] = W_i[s] \setminus W_j[s]$. Then the purpose of \mathcal{P}_e is to show that if R_e is a linearisation of \leq_P , then there exists a computable ζ -sequence in R_e . By construction, such a sequence will be made up of elements of P_e .

We will construct \mathcal{P}_e in such a way that any ζ -sequence in \mathcal{P}_e computes the halting set K , and is therefore not computable. Since there are no \leq_P -comparabilities between the components and each component has no computable ζ -sequence, we have that \mathcal{P} as a whole has no computable ζ -sequence.

At each stage s of the construction we define an approximation $\mathcal{P}[s]$ with domain some finite initial segment of \mathbb{N} , we also compute the approximations $R_e[s]$ for $e < s$ and an approximation $K[s]$ of the halting set, to be used in the construction. At stage 0, $\mathcal{P}[0] = \emptyset$, then at stage $s + 1$ we add up to six new elements to each $\mathcal{P}_e[s]$ with $e < s$ and eight new elements to $\mathcal{P}_s[s]$.

When a number n enters the construction at a stage s , all of the \leq_P -comparabilities of n with $k < n$ are set at stage s and do not change at any later stage. So each \mathcal{P}_e is computable because if we wish to compute \leq_P relative to a pair of numbers (n, m) then it suffices to run the construction until stage $s = \max\{n, m\} + 1$ and the approximation to \leq_P relative to (n, m) at stage s will be the true value, and hence \mathcal{P} is computable.

We now fix some $e \in \mathbb{N}$ and consider the construction of \mathcal{P}_e . At all stages $s \leq e$, $\mathcal{P}_e[s] = \emptyset$, then at stage $s = e + 1$, eight new elements are added to define $\mathcal{P}_e[s + 1]$. \mathcal{P}_e in this construction will consist of a copy of the construction from Theorem 2.14 and a copy of the dual of that construction. We call these copies \mathcal{D}_e and \mathcal{U}_e respectively, and everything in \mathcal{U}_e is \leq_P -greater than everything in \mathcal{D}_e .

\mathcal{D}_e has four elements with the comparabilities $b_{-1}^D <_P y^D <_P a_{-1}^D$ and $b_{-1}^D <_P x^D <_P a_{-1}^D$, and \mathcal{U}_e has four elements with the comparabilities $a_{-1}^U <_P y^U <_P b_{-1}^U$ and $a_{-1}^U <_P x^U <_P b_{-1}^U$ as shown in Figure 3.1.

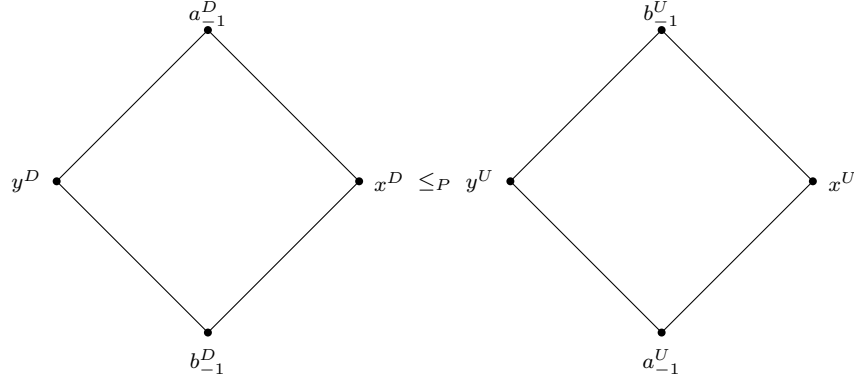


Figure 3.1: The first eight elements of \mathcal{P}_e added at stage $e + 1$

We then proceed to simultaneously construct both parts of the partial order as in the proof of Theorem 2.14 and dually as appropriate. We then get the outcomes as follows. If there are only finitely many good stages, then \mathcal{P}_e will be finite, and the necessary conditions for the theorem trivially hold, as it contains no ζ -sequence, and R_e is not a linearisation of \mathcal{P}_e . Indeed if R_e is a linearisation of \mathcal{P}_e then there will be infinitely many good stages for e , at each of which either two or four elements were added to \mathcal{P}_e , and hence \mathcal{P}_e would be infinite.

If \mathcal{P}_e is infinite, and R_e linearises \mathcal{P} , then we will have by construction a computable ζ -sequence in R_e , just by combining the sequences that we construct in each part of \mathcal{P}_e . The construction builds a computable ω^* -sequence σ in $\mathcal{L}(\mathcal{D}_e)$ and a computable ω -sequence τ in $\mathcal{L}(\mathcal{U}_e)$. Thus $\sigma + \tau$ is a computable ζ -sequence in $\mathcal{L}(\mathcal{P}_e)$ and so in $\mathcal{L}(\mathcal{P})$. Of course the sequences σ and τ may be extracted at different levels - i.e. σ may be computed at Level 1 and τ computed at Level 2, or visa versa. But this does not matter

for the proof.

In \mathcal{U}_e we can show that that below any given any element there are only finitely many elements in \mathcal{U}_e itself, and similarly above any element in \mathcal{D}_e . So any ζ -sequence in \mathcal{P}_e must lead to an ω^* -sequence in \mathcal{D}_e and an ω -sequence in \mathcal{U}_e , each of which computes K by construction.

Then as before, we can see that since e was arbitrary, we can see every 2-c.e. linear extension of \mathcal{P} computably embeds ζ , and any suborder of \mathcal{P} of order type ζ must compute K . And we have also seen that the construction of \mathcal{P} is entirely computable. This concludes the proof of the $n = 2$ case.

The generalisation to n -c.e. then occurs in exactly the same way as before, take a computable listing of n -c.e. sets R_e and associated approximations $R_e[s]$, and define n -computation as above. Work through the construction in each part as in the $n - 1$ case, but when something is n -computed we define the points $a_i^{D(n-1)}, b_i^{D(n-1)}, c_i^{D(n-1)}, d_i^{D(n-1)}$ or $a_i^{U(n-1)}, b_i^{U(n-1)}, c_i^{U(n-1)}, d_i^{U(n-1)}$ and redefine the Level n active interval as appropriate. If R_e linearises \mathcal{P} then will then be some $1 \leq t \leq n$ such that the Level t active interval is redefined infinitely often. Then t is the greatest of those, if R_e linearises \mathcal{P}_e then the $\{a_n^{(t-1)}\}_{n \in \mathbb{N}}$ will be a computable ζ -sequence in R_e .

However, any ζ -sequence in \mathcal{P}_e will compute K in the same way as discussed above, since the construction at the t level is computable and so we can use the position of the sequence relative to the $\{a_n^t\}_{n \in \mathbb{N}}$ to determine membership of elements of K .

Then for any n we can construct a witness \mathcal{P} which is computable and does not computably embed ζ , but has no n -c.e. linearisation which does not computably embed ζ . □

This construction fails for ω -c.e. for the same reasons as before. If there is no fixed bound on the number of times a pair can be changed in the linearisation, then there will not necessarily be a greatest t such that the Level t active interval is redefined infinitely often. In fact we could have no such t and just keep redefining intervals of greater and greater Level, but only finitely often. Thus we cannot build the computable ζ -sequence necessary in R_e and the argument fails.

Again, in the proof of this theorem, we construct a separate counterexample for each $n \geq 1$ for reasons of clarity. But it is in fact possible to build one witness which proves the theorem for all $n \geq 1$. To do this, as before, we need a listing of all n -c.e. sets, for all $n \geq 1$, which we define $\{R_{\langle n,e \rangle}\}_{n,e \in \mathbb{N}}$ with uniform approximations $\{R_{\langle n,e \rangle}[s]\}_{n,e,s \in \mathbb{N}}$.

Let $g : \mathbb{N}^3 \rightarrow \mathbb{N}$ be a computable function such that

$$W_{g(n,e,k)} = \begin{cases} \bigcap_{0 \leq i \leq k} W_{e_i} & \text{if } 0 \leq k \leq n \text{ (where } e = \langle e_0, e_1, \dots, e_{n-1} \rangle), \\ \emptyset & \text{if } k > n. \end{cases}$$

Note that n determines the length of the tuple coded as e , and if $n = 0$ then we use the convention that $e = \langle e \rangle$, so $e_0 = e$.

Then

$$R_{\langle n,e \rangle} = \bigcup_{i=0}^{\lfloor \frac{n}{2} \rfloor} W_{g(n,e,2i)} \setminus W_{g(n,e,2i+1)},$$

and $R_{\langle n,e \rangle}[s]$ is defined using the stage s approximations to all the of c.e. sets involved.

The construction then proceeds in the same way as before, with $\mathcal{P}_{\langle e,n \rangle}$ being the component of the witness which shows that if $R_{\langle e,n \rangle}$ is a linearisation of \mathcal{P} then there exists a computable ζ -sequence in $R_{\langle e,n \rangle}$. Notice that because n is encoded in the index

of $\mathcal{P}_{\langle e,n \rangle}$, we can computably determine which algorithms from the above proofs to use in the construction, and hence the construction remains computable. In effect we simultaneously perform the constructions for the proof for each $n \geq 1$.

We can improve this result, pushing the bound further up using a similar type of proof. In order to do so, we need a way of Δ_2 -approximating the sets of a wider class than n -c.e. and so we take the following definition and lemma from Badillo and Harris 2014 [2].

Definition 3.6.

A class of sets $C \subseteq \mathcal{P}(\mathbb{N})$ is *uniform* Δ_2 if there is a binary function $f \leq_T \emptyset'$ such that the class F of characteristic functions of C satisfies $F = \{f_e \mid e \in \mathbb{N}\}$. Hence C is uniform Δ_2 if and only if there exists a uniform Δ_2 approximation $\{A_{e,s}\}_{e,s \in \mathbb{N}}$ such that $C = \{A_e\}_{e \in \mathbb{N}}$.

Note that this definition corresponds to the notion of \emptyset' -uniform in the notation used by Jockush [20].

Lemma 3.7 (Ershov 1968 [13]).

For any computable ordinal α , the class of α -c.e. sets is uniform Δ_2 .

Corollary 3.8.

The class of ω -c.e. sets is uniform Δ_2 .

Given the existence of a uniform Δ_2 approximation of the class of ω -c.e. sets, we can now improve the bound to ω -c.e.

Theorem 3.9.

The order type ζ is not ω -c.e.-extendible.

Proof. We construct as a witness a computable partial order $\mathcal{P} = (\mathbb{N}, \leq_{\mathcal{P}})$ as the disjoint union of sub-partial orderings \mathcal{P}_e such that each \mathcal{P}_e forms a connected component of \mathcal{P} ,

and in particular every element of \mathcal{P}_e is incomparable to every element of every other \mathcal{P}_f where $e \neq f$. We will assume a listing of ω -c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, and an associated Δ_2 approximation $\{R_e[s]\}_{e, s \in \mathbb{N}}$, since we know that the class of ω -c.e. sets is uniform Δ_2 by Corollary 3.8. Then the purpose of \mathcal{P}_e is to show that if R_e is a linearisation of \leq_P , then there exists a computable ζ -sequence in R_e . By construction, such a sequence will be made up of elements of \mathcal{P}_e .

At each stage s of the construction we define an approximation $\mathcal{P}[s]$ with domain some finite initial segment of \mathbb{N} and we also compute the approximations $R_e[s]$ for $e < s$. At stage 0, $\mathcal{P}[0] = \emptyset$, then at stage $s + 1$ we two new elements to each $\mathcal{P}_e[s]$ with $e \leq s$.

When a number n enters the construction at a stage s , all of the \leq_P -comparabilities of n with $k < n$ are set at stage s and do not change at any later stage. So each \mathcal{P}_e is computable because if we wish to compute \leq_P relative to a pair of numbers (n, m) then it suffices to run the construction until stage $s = \max\{n, m\} + 1$ and the approximation to \leq_P relative to (n, m) at stage s will be the true value, and hence \mathcal{P} is computable.

We now fix some $e \in \mathbb{N}$ and consider the construction of \mathcal{P}_e . At all stages $s \leq e$, $\mathcal{P}_e[s] = \emptyset$, then at stage $s = e + 1$, two incomparable elements a_e, b_e are added to define $\mathcal{P}_e[s + 1]$.

Then at future stages s where $R_e[s]$ decides the order of a_e, b_e (i.e. exactly one of $a_e R_e[s] b_e$ and $b_e R_e[s] a_e$ holds), add two new points. Assuming without loss of generality that $a_e R_e[s] b_e$, we add a new point which is \leq_P -above b_e and all points which are \leq_P -above b_e , and another point which is \leq_P -below a_e and all points which are \leq_P -below a_e . I.e. extending a chain above b_e and a chain below a_e .

$\{R_e[s]\}_{s \in \mathbb{N}}$ is a Δ_2 approximation, so it eventually settles on the order of a_e, b_e ,

and if R_e is a linearisation then there will be infinitely many points in \mathcal{P}_e . So if \mathcal{P}_e is infinite then it looks like an ω chain and an ω^* chain which are mutually incomparable, but form a computable ζ chain in R_e .

Then as before, we can see that since e was arbitrary, we can see the \mathcal{P} does not embed ζ but every ω -c.e. linear extension computably embeds ζ . And we have also seen that the construction of \mathcal{P} is entirely computable, and this concludes the proof. \square

In fact this result can be further improved to Δ_2 , although the class of Δ_2 sets is not uniform Δ_2 , so the same proof will not work. We have to modify it slightly.

Lemma 3.10 (Lee, Harris and Cooper 2011 [29]).

For any Σ_2 set A of codings of computable ordinals¹, the class of Ac.e. sets $\Sigma_A^{-1} = \bigcup_{a \in A} \Sigma_a^{-1}$ is uniform Δ_2 .

Theorem 3.11.

The order type ζ is not Δ_2 -extendible.

Proof. Whilst the class of α -c.e. sets is uniformly Δ_2 approximable for any computable ordinal α , the class of Δ_2 sets is not. However, we can construct a Σ_2 approximation to the class of Σ_2 sets, noting that a Σ_2 linear order with computably presented domain is in fact Δ_2 (just as Σ_1 linear orders with computably presented domain are computable).

Specifically we construct a uniform Σ_2 approximation $\{R_e[s]\}_{e,s \in \mathbb{N}}$ of the sets $R_e = \{n \mid \exists s \forall t \geq s R_e(n)[t] = 1\}$ such that R is an infinite Δ_2 set if and only if $R = R_e$ for some e . In the context of orderings, the approximation will eventually decide that $aR_e b$, but may also switch between $bR_e a$ and $b \not R_e a$ infinitely often, though if it does converge, then it will be on $b \not R_e a$.

¹The coding is performed using Kleene's \mathcal{O} , but we suppress the details as they are not needed here.

The construction is much the same as above, but has some vital differences. We construct as a witness a computable partial order $\mathcal{P} = (\mathbb{N}, \leq_P)$ as the disjoint union of sub-partial orderings \mathcal{P}_e such that each \mathcal{P}_e forms a connected component of \mathcal{P} , and in particular every element of \mathcal{P}_e is incomparable to every element of every other \mathcal{P}_f where $e \neq f$. We will use our Σ_2 approximations $\{R_e[s]\}_{e,s \in \mathbb{N}}$. Then the purpose of \mathcal{P}_e is to show that if R_e is a linearisation of \leq_P , then there exists a computable ζ -sequence in R_e . By construction, such a sequence will be made up of elements of \mathcal{P}_e .

At each stage s of the construction we define an approximation $\mathcal{P}[s]$ with domain some finite initial segment of \mathbb{N} and we also compute the approximations $R_e[s]$ for $e < s$. At stage 0, $\mathcal{P}[0] = \emptyset$, then at stage $s + 1$ we two new elements to each $\mathcal{P}_e[s]$ with $e \leq s$.

When a number n enters the construction at a stage s , all of the \leq_P -comparabilities of n with $k < n$ are set at stage s and do not change at any later stage. So each \mathcal{P}_e is computable because if we wish to compute \leq_P relative to a pair of numbers (n, m) then it suffices to run the construction until stage $s = \max\{n, m\} + 1$ and the approximation to \leq_P relative to (n, m) at stage s will be the true value, and hence \mathcal{P} is computable.

We now fix some $e \in \mathbb{N}$ and consider the construction of \mathcal{P}_e . At all stages $s \leq e$, $\mathcal{P}_e[s] = \emptyset$, then at stage $s = e + 1$, two incomparable elements a_e, b_e are added to define $\mathcal{P}_e[s + 1]$.

This is the point at which the proof diverges from the proof of Theorem 3.9. At stage s , if $a_e R_e[s] b_e$ and $a_e \not R_e[s - 1] b_e$ then two new points are added, one directly above b_e and not above any other point above b_e , and one directly below a_e and not below any other point below a_e . However, if $a_e R_e[s] b_e$ and $a_e R_e[s - 1] b_e$ then two new points are added, one above the point added above b_e at stage $s - 1$, and one below the point added below a_e at stage $s - 1$.

Similarly, at stage s , if $b_e R_e[s] a_e$ and $b_e \not/R_e[s-1] a_e$ then two new points are added, one directly above a_e and not above any other point above a_e , and one directly below b_e and not below any other point below b_e . However, if $b_e R_e[s] a_e$ and $b_e R_e[s-1] a_e$ then two new points are added, one above the point added above a_e at stage $s-1$, and one below the point added below b_e at stage $s-1$.

The reason for this construction is that R_e may change its mind on the order of a_e, b_e infinitely often, and if we used the construction in Theorem 3.9, we would have ζ embedding in \mathcal{P}_e . But if we start a new chain every time R_e changes its mind, we avoid this possibility, since by the nature of the approximation, at most one pair of chains can be infinitely long, and this occurs exactly when R_e is a linear extension of \mathcal{P}_e .

Hence, we cannot embed ζ in \mathcal{P}_e and hence we cannot embed ζ in \mathcal{P} , but if R_e linearises \mathcal{P} then it contains a computable embedding of ζ , constructed in the same way as before. Recall that a Σ_2 linear order is in fact Δ_2 , and we have that any Δ_2 linearisation of \mathcal{P} computably embeds ζ , and \mathcal{P} is a computable partial order which does not embed ζ , as required. \square

Chapter 4

Scattered orderings

In this chapter we consider orderings which are scattered, that is have no dense suborder. There is less previously known in this area, but we show that in fact the same bounds apply as to well-founded orderings. Every computably scattered computable partial order has a computably scattered ω -c.e. linear extension, but for any $n \in \mathbb{N}$, there is a computably scattered computable partial order which has no computably scattered n -c.e. linear extension.

4.1 Background

Definition 4.1.

We call a partial order \mathcal{P} *scattered* if \mathcal{P} does not embed η , the order type of the rational numbers. We say \mathcal{P} is *computably scattered* if there is no computable embedding of η in \mathcal{P} .

The classical result was proved by Bonnet and Pouzet, and independently by Galvin and McKenzie (unpublished), in the late 1960's as part of a larger program. The proof we

give is not from the original paper, but from Bonnet and Pouzet's 1981 survey of linear extension theory [5].

Definition 4.2.

If \mathcal{P} is a partial order, and \mathcal{I} is a suborder of \mathcal{P} , we say that \mathcal{I} is an *initial segment* of \mathcal{P} if for any $x, y \in \mathcal{P}$, if $y \in \mathcal{I}$ and $x \leq_{\mathcal{P}} y$ then $x \in \mathcal{I}$.

Definition 4.3 (Corominas).

A non-empty partial order \mathcal{P} is called an η -kernel if no non-empty initial or final segment of \mathcal{P} (with the induced order) has a scattered linear extension.

Lemma 4.4.

If \mathcal{P} has no scattered linear extension, then it contains an η -kernel.

Proof. Let $G(\mathcal{P})$ be the set of initial segments \mathcal{I} of \mathcal{P} which have scattered linear extensions $\mathcal{L}(\mathcal{I})$. Then if $\mathcal{A} \subseteq \mathcal{I} \in G(\mathcal{P})$, we must have that \mathcal{A} has a scattered linear extension, although it may not be an initial segment and hence may not be in $G(\mathcal{P})$. Also, if $\mathcal{I}, \mathcal{J} \in G(\mathcal{P})$, then $\mathcal{I} \cup \mathcal{J}$ is an initial segment of \mathcal{P} , and it has a scattered linear extension, which we construct by the order-theoretic sum of the scattered linear extension of \mathcal{I} and the scattered linear extension of $\mathcal{J} \setminus \mathcal{I}$. Hence, $G(\mathcal{P})$ is closed under finite unions.

Also if $(\mathcal{I}_\alpha)_{\alpha < \delta}$ is a well-ordered increasing sequence of elements of $G(\mathcal{P})$ then the union $\mathcal{I} = \bigcup_{\alpha < \delta} \mathcal{I}_\alpha$ is in $G(\mathcal{P})$, since it has scattered linear extension built by the order-theoretic sum of the scattered linear extensions of the partial unions. Hence, $G(\mathcal{P})$ is closed under arbitrary unions, since they will be finite unions of unions of chains of initial segments, and so has a largest element $\hat{\mathcal{I}} = \bigcup G(\mathcal{P})$.

Similarly, there is a largest final segment of \mathcal{P} which has a scattered linear extension, call it $\hat{\mathcal{F}}$. Let $\mathcal{N} = \mathcal{P} \setminus (\hat{\mathcal{I}} \cup \hat{\mathcal{F}})$ with the induced order, and then \mathcal{N} is an η -kernel. Note that \mathcal{N} is not empty, because otherwise $\mathcal{P} = \hat{\mathcal{I}} \cup \hat{\mathcal{F}}$ and then \mathcal{P} would have a scattered linear extension. □

Lemma 4.5.

If \mathcal{P} contains an η -kernel then it is not scattered.

Proof. Let $\mathcal{P}_{\frac{1}{2}}$ be a partial order containing an η -kernel $\mathcal{N}_{\frac{1}{2}}$. Choose an element $x_{\frac{1}{2}} \in \mathcal{N}_{\frac{1}{2}}$ and let $\mathcal{P}_{\frac{1}{4}} = \{x \in \mathcal{N}_{\frac{1}{2}} \mid x \leq_{\mathcal{P}_{\frac{1}{2}}} x_{\frac{1}{2}}\}$ and $\mathcal{P}_{\frac{3}{4}} = \{x \in \mathcal{N}_{\frac{1}{2}} \mid x \geq_{\mathcal{P}_{\frac{1}{2}}} x_{\frac{1}{2}}\}$, with the induced orderings.

Since $\mathcal{N}_{\frac{1}{2}}$ is an η -kernel, $\mathcal{P}_{\frac{1}{4}}$ and $\mathcal{P}_{\frac{3}{4}}$ have no scattered linear extensions, and hence contain non-empty η -kernels $\mathcal{N}_{\frac{1}{4}}$ and $\mathcal{N}_{\frac{3}{4}}$ respectively, from which we choose elements $x_{\frac{1}{4}}$ and $x_{\frac{3}{4}}$ and continue the process to define a sequence $(x_d)_{d \in D}$ of elements of $\mathcal{P}_{\frac{1}{2}}$ where the indexing set D is the set of dyadic numbers¹. These elements form a subset of $\mathcal{P}_{\frac{1}{2}}$ with order type η , and hence $\mathcal{P}_{\frac{1}{2}}$ is not scattered. \square

Theorem 4.6 (Bonnet and Pouzet 1969 [4]).

Any scattered partial order has a scattered linear extension. I.e. η is extendible.

Proof. The proof of this theorem then immediately follows by a contrapositive argument on the conjunction of the two lemmas. \square

This forms part of the general classification by Bonnet [3] of countable order types τ such that a partial order which does not embed τ can always be extended to a linear order which does not embed τ . The effective content of this theorem differs slightly from the well-founded case, as Corollaries 4.9 and 4.8 to the following theorem of Downey, Hirschfeldt, Lempp and Solomon demonstrates.

Theorem 4.7 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

There is a scattered computable partial ordering such that every computable linear extension has a computable densely ordered subchain.

¹The dyadic numbers are those rational numbers with a denominator which is a power of 2, so $D = \frac{1}{2}, \frac{1}{4}, \frac{3}{4}, \frac{1}{8}, \dots$

Proof. We show that, given a sequence $X_0 \leq_T X_1 \leq_T \dots$ of uniformly low, uniformly Δ_2^0 -sets, there is a scattered computable partial ordering $\mathcal{P} = (P, \leq_P)$ such that for any $i \in \omega$, any X_i -computable linear extension \leq_L of \leq_P contains a densely ordered \leq_L -subchain, computable in \leq_L .

We construct \mathcal{P} using a finite-injury priority argument, as the disjoint union of $\mathcal{P}_{i,e}$ for $i, e \in \omega$. Each $\mathcal{P}_{i,e}$ will be a connected component of \mathcal{P} , when \mathcal{P} is viewed as a directed graph, and has the purpose of showing that if the e -th binary X_i -computable relation $\mathcal{L}_{i,e} = L_e^{X_i}$ is a linear extension \leq_L of \leq_P then there is a set of elements of $\mathcal{P}_{i,e}$ which form a densely ordered subchain in \leq_L which is computable in $\mathcal{L}_{i,e}$. Since we are assuming that X_i is low, uniformly in i , we may assume that $L_e^{X_i}$ is either total or finite, and thus \leq_L can be effectively approximated.

Note that any dense \leq_P -subchain in \mathcal{P} must be contained in one $\mathcal{P}_{i,e}$ and so we show that this in fact cannot happen, and therefore \mathcal{P} is scattered. We do this by constructing $\mathcal{P}_{i,e}$ such that for any $x \in \mathcal{P}_{i,e}$, there are either only finitely many elements $\geq_P x$ or only finitely many elements $\leq_P x$.

Fixing i and e , we construct $\mathcal{P}_{i,e}$ in stages, the full construction will computably interleave the constructions of each part. At stage 0 take three \leq_P -incomparable elements a_0, a_1, a_2 , call them 0-critical and wait for $\mathcal{L}_{i,e}$ to decide the \leq_L -ordering on them. Assume without loss of generality (relabelling as necessary) that $a_0 \leq_L a_1 \leq_L a_2$ and then place a_1 into a set C , and call $(-\infty, a_0)$ and (a_2, ∞) the 0-active intervals.

At stage $s + 1$ we enumerate three new \leq_P -incomparable elements within each s -active interval, look for the \leq_L -ordering on them, put the middle one into C and define the $s + 1$ -active intervals as between the outer two of the $s + 1$ -critical elements and the ends of the s -active interval. Note that if at any stage $\mathcal{L}_{i,e}$ does not converge on the

\leq_L -ordering of the s -critical elements then $P_{i,e}$ will just be finite.

The approximation of $\mathcal{L}_{i,e}$ may make finitely many mistakes before converging. Each time the approximation $L_e^{X_i}[s]$ changes its mind on a critical interval, the construction throws away the elements that depended on $a_0 \leq_L a_1 \leq_L a_2$ and starts the construction again from that point.

If $P_{i,e}$ is infinite then this process builds C to be a \leq_L -computable densely \leq_L -ordered chain, and hence \mathcal{L} is not scattered, but for any element $x \in \mathcal{P}$, there are either only finitely many elements $\geq_P x$ or finitely many elements $\leq_P x$, and so \mathcal{P} is scattered.

Because \leq_L can be effectively approximated (because it is computable in a low set), the construction of $\mathcal{P}_{i,e}$, and hence the construction of \mathcal{P} , will be computable, as if $\mathcal{L}_{i,e}$ is a linearisation of \mathcal{P} then it will converge on the order of the elements we add at each stage, and otherwise $\mathcal{P}_{i,e}$ will just be finite.

Since i, e were arbitrary, we see that \mathcal{P} has no dense suborder, and any X_i -computable linear extension \leq_L of \leq_P contains a densely ordered \leq_L -subchain, computable in \leq_L . □

We can simplify this, since we don't actually need to use the sequence of uniformly low, uniformly Δ_2 sets, as we're not interested in what is implied by WKL_0 . Instead just let \mathcal{P} be the disjoint union of \mathcal{P}_e , where each \mathcal{P}_e ensures that the e -th computable binary relation either is not a linear extension of \leq_P or contains a computable dense subchain.

Theorem 4.7 immediately implies the following two corollaries, just by weakening the conditions in the statement in one way or another.

Corollary 4.8 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

There is a scattered computable partial ordering that has no scattered computable linear extension.

Corollary 4.9 (Downey, Hirschfeldt, Lempp and Solomon 2003 [12]).

There is a computably scattered computable partial ordering that has no computably scattered computable linear extension.

Corollary 4.8 shows a key difference relative to the situation for well-founded orderings, for which we have that any well-founded computable partial ordering has a well-founded computable linear extension, by Theorem 2.5 of Rosenstein and Kierstead [43]. Corollary 4.9, on the other hand, is analogous to the well-founded case proved by Rosenstein and Statman [43].

The difference between Corollary 4.8 and Theorem 2.3 raises the question of at what level of complexity there is always a scattered linear extension of a scattered computable partial order. A bound must exist here and we conjecture that a bound of Δ_2 should be provable, although it is more difficult to construct a scattered linearisation than a computably scattered linearisation. This is because we cannot diagonalise against a list of c.e. sets, so different machinery would be needed.

Conjecture 4.10.

Every scattered computable partial order has a scattered Δ_2 linear extension.

Regarding scattered orderings, Rosenstein [43] claims the following Theorem 4.13 for the computable case, suggesting that the proof is by a similar argument to his theorem for computably well-founded orderings, but not providing it. Downey mentions the theorem in [11], citing Rosenstein [43] but also does not give the proof. We provide a proof below, but it has subtleties compared to the well-founded case which Rosenstein did not mention.

It seems Rosenstein intends to use the c.e. sets W_e and for each, if it is infinite, find a \leq_P -incomparable pair and force them to be a \leq_L -successive pair, with nothing in the linearisation in between them. However this runs up against the problem of recognising when a c.e. set will in the limit be dense, since naively at any finite stage, any ordering looks like it may be eventually dense. In order to get around this problem, which Rosenstein did not address, we introduce the concept of η -sequences.

Definition 4.11.

Let $\mathcal{P} = (\mathbb{N}, \leq_P)$ be a partial (possibly linear) ordering. If W_e is infinite, and $x_0^e, x_1^e, x_2^e, \dots$ is a canonical enumeration of W_e , then say W_e defines a η -sequence in \leq_P if the x_i^e form a chain in \mathcal{P} , and they are enumerated into \mathcal{P} in the following way.

We use the standard binary tree coding of $\{0, 1\}^*$, as shown in Figure 4.1, and define a bijection $b : \mathbb{N} \rightarrow \{0, 1\}^*$ by setting $b(n) = \sigma \iff [1 \frown \sigma]_2 = n + 1$. That is, $b(n) = \sigma$ if and only if appending the bit 1 to the beginning of σ gives the binary number equal to $n + 1$. Figure 4.2 shows the tree after the map from finite binary sequences to natural numbers.

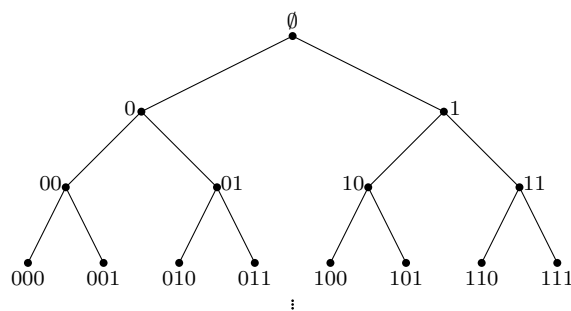


Figure 4.1: Coding of finite binary strings on a binary tree

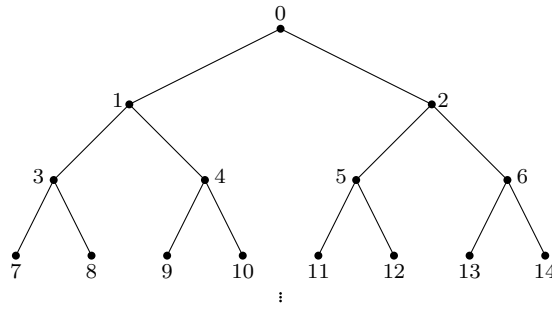


Figure 4.2: Coding of indices on a binary tree

Now, we say that W_e defines a η -sequence in \leq_P if the indices of the elements of W_e in the order in which they are enumerated, fit the pattern on the tree. That is odd-indexed elements x_{2n+1}^e are added to the chain as immediate \leq_P -predecessors of the element indexed by the number immediately above $2n + 1$ on the tree, and even-indexed elements x_{2n}^e are added to the chain as immediate \leq_P -successors of the element indexed by the number immediately above $2n$ on the tree.

So for example, the first 10 elements of a W_e which defines an η -sequence will be enumerated into \mathcal{P} with the ordering

$$x_7^e <_P x_3^e <_P x_8^e <_P x_1^e <_P x_9^e <_P x_4^e <_P x_0^e <_P x_5^e <_P x_2^e <_P x_6^e.$$

Lemma 4.12.

A computable partial ordering $\mathcal{P} = (\mathbb{N}, \leq_P)$ is computably scattered if and only if for all $e \in \mathbb{N}$, W_e does not define a η -sequence in \leq_P .

Proof. If \mathcal{D} is a computable dense subordering of \mathcal{P} without endpoints, then a computable subset of \mathcal{D} can be enumerated as a η -sequence. Conversely a c.e. set which enumerates a η -sequence in \mathcal{P} contains a dense computable set. □

This idea essentially gives us a “canonical” enumeration of η , in the sense that we only

need look for one particular computable enumeration of η to ensure there is no computable copy of η present.

Theorem 4.13 (Rosenstein and Statman 1984 [43]).

Any computably scattered computable partial order has a computably scattered Δ_2 linear extension.

Proof. Given a computably scattered, computable partial order $\mathcal{P} = (P, \leq_P)$ (and assuming for simplicity that $P = \mathbb{N}$) we construct a linearisation \mathcal{L} to be computably scattered, and consider how complicated it need be.

We construct \mathcal{L} by enumerating numbers in turn as high as possible into \mathcal{L} whilst respecting \mathcal{P} . To ensure that \mathcal{L} is computably scattered it suffices to guarantee that no W_e enumerates a η -sequence in \mathcal{L} . In order to ensure that the subordering induced on W_e is not a η -sequence, we find some x_i^e, x_{i+1}^e which are either \leq_P -comparable and witness that W_e does not define an η -sequence or that are \leq_P -incomparable. If W_e is infinite then we will always be able to eventually find some x_i^e, x_{i+1}^e , and place them into \mathcal{L} to prevent W_e from defining an η -sequence, as otherwise W_e will be a dense subordering of \mathcal{P} .

We can use the first x_i^e, x_{i+1}^e enumerated that are \leq_P -incomparable for this purpose, if the enumeration of W_e up to that point looks like a η -sequence. For any infinite W_e there will be some finite stage in its enumeration at which there will either be a \leq_P -incomparable pair, or a pair which stops W_e from looking like a η -sequence, due to the fact that \mathcal{P} is computably scattered.

So, as in the proof of Theorem 2.7, the oracle we need is one to tell us whether W_e is infinite. So we again get the construction of \mathcal{L} being computable in a Σ_1 -set, and the result follows. \square

4.2 The upper bound

We can use the concept of η -sequences and adapt the argument of Theorem 2.8 to the scattered case in a mostly straightforward way, to lower the upper bound from Δ_2 to ω -c.e. analogously to the well-founded case in the previous chapter.

Theorem 4.14.

The order type η is computably ω -c.e.-extendible. That is, every computably scattered computable partial order has a computably scattered ω -c.e. linear extension.

Proof. Let $\mathcal{P} = (\mathbb{N}, \leq_P)$ be a computable partial order that is computably scattered. We build a linearisation \mathcal{L} of \mathcal{P} as the limit of a uniformly computable sequence of finite linear orderings $(\mathcal{L}_s = (\mathbb{N} \upharpoonright_s, \leq_{L,s}))_{s \in \omega}$, such that the limit $\lim_{s \rightarrow \infty} \leq_{L,s} = \leq_L$ exists and is a linear extension of \leq_P .

By examining the construction, we shall show there is a computable bound on the number of changes to each element of $\leq_{L,s}$, that is the set of s such that $\leq_{L,s}$ does not agree with $\leq_{L,s+1}$ on given $a, b \in \mathbb{N}$ is bounded by a computable function in a and b (and so in $\langle a, b \rangle$). Hence, the limit $\leq_L = \lim_{s \rightarrow \infty} \leq_{L,s}$ is ω -c.e.

Let W_e be the e -th computably enumerable set, under the standard listing and let $x_0^e, x_1^e, x_2^e, \dots$ be the elements of W_e in the order they are enumerated. Clearly, if $(y_i)_{i \in \omega}$ is a computable sequence, then there is some e such that $y_i = x_i^e$ for all i .

By Lemma 4.12, to ensure that \mathcal{L} is computably scattered, it suffices to ensure that no sequence $(x_i^e)_{i \in \omega}$ defines a η -sequence in \mathcal{L} . As in the proof of Theorem 4.13 we achieve this for each infinite W_e by finding some $x_i^e, x_{i+1}^e \in W_e$ such that either they are \leq_P -comparable and are not part of an η -sequence, or $x_i^e \not\leq_P x_{i+1}^e$ and swapping them around to ensure that W_e cannot define a η -sequence.

If W_e would define an η -sequence in \mathcal{L} if we did not act to prevent it, then such x_i^e, x_{i+1}^e must exist as otherwise W_e would define an η -sequence in \mathcal{P} , contradicting the assumption that \mathcal{P} is computably scattered.

4.2.1 Requirements

The construction will satisfy the following requirements, for $e \in \omega$,

N : \mathcal{L} is a linear extension of \mathcal{P} .

R_e : W_e does not define a η -sequence in \leq_L .

The requirements are ordered in the priority ordering $N \succ R_0 \succ R_1 \succ R_2 \succ \dots$.

4.2.2 Strategy

We ensure that \mathcal{L} is a linear extension of \mathcal{P} by defining at every stage \mathcal{L}_s to be a linear extension of $\mathcal{P} \upharpoonright_s$. Then to ensure that the limit $\lim_{s \rightarrow \infty} \mathcal{L}_s$ exists, we restrain the requirement R_e from acting on $\leq_{L_s} \upharpoonright_e$. So only finitely many requirements can modify any part of \leq_{L_s} , and since we will show each requirement can only act finitely often, the limit exists. This also gives a computable bound on the number of changes, and hence that the ordering \leq_L is ω -c.e.

For each requirement R_e , we set a restraint threshold $t_e[s]$, which is the \mathbb{N} -greatest number which R_e needs preserved from future alteration in order to ensure it remains satisfied, at the beginning of stage s . We also define the restraint $T_e[s] = \{n \in \mathbb{N} \mid n \leq_{\mathbb{N}} \max\{t_{e'}[s] \mid e' < e\}\}$, which is the portion of $\leq_{L,s}$ which R_e is not permitted to alter, in order to avoid injuring higher priority requirements. In fact we restrict R_e from changing the order of any element of the linearisation with any element

of the restraint.

To satisfy R_e , we look for elements $x_i^e, x_j^e \geq_{\mathbb{N}} e$, such that either they are \leq_P -comparable and prevent W_e from defining a η -sequence, or they are \leq_P -incomparable and such that we can swap them around without affecting $\langle_{L,s+1} \upharpoonright T_e[s]$, in particular that there is no element of the restraint between them, and therefore without injuring the restraint of any higher priority requirement. We will argue that if W_e is infinite, then we will eventually find some suitable pair of elements.

In the first case, if we find a pair of elements which prevent W_e from defining a η -sequence, then we say that R_e has been discharged, and move on.

In the second case, we plummet the element x_i^e , called the *plummet witness*, $\leq_{L,s-1}$ -below x_j^e as follows. Suppose that $x_j^e = c_k \leq_{L,s-1} \cdots \leq_{L,s-1} c_1$ is a list in \mathcal{L}_{s-1} of the finite set

$$\{c \mid c \in \mathcal{L}_{s-1} \text{ and } x_j^e \leq_{L,s-1} c <_{L,s-1} x_i^e \text{ and } c \not\leq_P x_i^e\}$$

and notice that clearly $c_n \not\leq_P x_i^e$ for all c_n (and therefore c_n is also \leq_P -incomparable with any element \leq_P -comparable to x_i^e), since $\leq_{L,s-1}$ extends \leq_P on the elements already enumerated.

Now, for any $c_1 \leq_{L,s-1} d \leq_{L,s-1} x_i^e$, we must have that $d \leq_P x_i^e$ but by definition $c_1 \not\leq_P x_i^e$ and therefore $c_1 \not\leq_P d$. Denote by $x_i^e + 1$ the immediate successor of x_i^e in \mathcal{L}_{s-1} if it exists and move c_1 until $x_i^e \leq_{L,s} c_1 \leq_{L,s} x_i^e + 1$. Then by the same argument, we can repeat the process for all c_i to get $x_i^e \leq_{L,s} c_k \leq_{L,s} \cdots \leq_{L,s} c_1 \leq_{L,s} x_i^e + 1$. If the successor $x_i^e + 1$ does not exist then just move c_1 to immediately above x_i^e and then proceed as if $c_1 = x_i^e + 1$.

Notice that since $x_j^e = c_k$, at the end of stage s we have $x_i^e \leq_{L,s} x_j^e$, and hence

$W_{e,s}$ is not an η -sequence. Now set $t_e[s+1] = \max\{x_i^e, x_j^e\}$. After we have completed the plummeting, we say that R_e is discharged.

4.2.3 Construction

At stage 0, set $t_e[0] = 0$ for all e .

At stage $2s+1$ we enumerate the number s into \mathcal{L}_s , as high as possible² whilst ensuring that \mathcal{L}_s is a linear extension of $\mathcal{P} \upharpoonright_s$, and whilst not placing s inbetween any pair of elements which is witnessing some R_e .

We say that R_e *requires attention* at stage s if the elements of $W_{e,s}$ describe the start of a η -sequence in \leq_L , and R_e can be satisfied at stage s , i.e. there are two elements $x_i^e, x_j^e >_{\mathbb{N}} T_e[s]$ which are \leq_P -incomparable, greater than $T_e[s]$ and do not have an element of the restraint for e between them in \mathcal{L}_{s-1} , or if there is a pair of elements $x_i^e <_P x_j^e$ which prevent W_e from defining an η -sequence and W_e has not been already discharged.

At stage $2s+2$ we find the least e such that R_e requires attention (if no such e exists then end the stage and go on to stage $2s+3$). If W_e requires attention because there is a pair of elements $x_i^e <_P x_j^e$ which prevent W_e from defining an η -sequence, then say R_e is discharged and move on to stage $2s+3$.

Otherwise take the elements x_i^e, x_j^e as described above and if, without loss of generality, $x_i^e \leq_{L,s} x_j^e$, then plummet x_j^e as described above in order to get $x_j^e \leq_{L,s+1} x_i^e$. This ensures that W_e does not define a η -sequence, but \mathcal{L}_{s+1} is still a linear extension of $\mathcal{P} \upharpoonright_s$.

²Enumerating elements as high as possible is an arbitrary choice, it would be equally valid to enumerate as low as possible or in some other way as long as it is compatible with the partial order.

Then say R_e has been discharged and move on to stage $2s + 3$. Note that it is possible that a higher priority requirement will act later to undo this switch, and in that case R_e stops being discharged and may again require attention.

4.2.4 Verification

Lemma 4.15.

\mathcal{L} is a linear extension of \mathcal{P} .

Proof. At every stage \mathcal{L}_s is defined to be a linear extension of $\mathcal{P} \upharpoonright_s$, and any finite initial segment of the linearisation is fixed after a finite number of stages, so the limit $\lim_{s \rightarrow \infty} \mathcal{L}_s = \mathcal{L}$ exists, and is a linear extension of \mathcal{P} . \square

Lemma 4.16.

\mathcal{L} is computably scattered.

Proof. If \mathcal{L} were not computably scattered then there would be some computable subchain of \mathcal{L} which had order type η . And so there would be some computably enumerable set W_e which enumerated this subchain as a η -sequence, and so the requirement R_e would not be satisfied.

Let s_0 be a stage such that $T_e[s]$ is fixed for all $s \geq s_0$, which exists because the requirements with higher priority can only act a finite number of times. We can show this by induction on e , obviously R_0 only acts at most once, then assuming that $R_{e'}, e' < e$ act finitely often, we see that R_e must act at most once more than the combined number of actions of all $R_{e'}$, which will also be finite. Hence, s_0 exists. Then we argue that R_e is satisfied after s_0 .

We suppose that W_e is infinite, because if W_e is finite then R_e is trivially satisfied.

If the finite part of W_e which has been enumerated by stage s_0 does not define the start of a η -sequence, then R_e will be satisfied, so suppose it does. Then if R_e is never satisfied, the enumeration of W_e after stage s_0 must go on to define a η -sequence, and never require attention (because if it did then R_e would act to satisfy itself with highest priority), and so it must be the case that there is no pair $x_i^e, x_j^e \geq_{\mathbb{N}} T_e[s]$ which is incomparable in \mathcal{P} and without any number less than $T_e[s]$ between them in \mathcal{L} . But then since $T_e[s]$ is finite, there will be a dense subset of W_e which is entirely between two successive points in the threshold $T_e[s]$. This subset will define a computable η -sequence in \mathcal{P} , which contradicts the fact that \mathcal{P} is computably scattered.

Hence, all requirements R_e are satisfied and \mathcal{L} is computably scattered. \square

Lemma 4.17.

\mathcal{L} is ω -c.e.

Proof. If R_e acts at stage s , it will remain satisfied and will not act again at a subsequent stage, unless it is injured by a requirement with higher priority. Hence, any requirement will act at most 2^e times. Since R_e cannot make changes to \leq_{L_s} for numbers $\leq e$, $\leq_{B,s} \upharpoonright_e$ can change at most $2^e - 1$ times, and so changes in \leq_L are computably bounded, and \mathcal{L} is ω -c.e. \square

This completes the proof of Theorem 4.14. \square

4.3 The lower bound

The n -c.e. lower bound result also carries over from well-founded to scattered orderings, but the proof simplifies considerably, because rather than needing any dense suborders to compute the Halting set, we can just construct the witness to have no dense suborders. We couldn't, in the well-founded case, create the order without any infinite descending chains because of König's Lemma, but here we can construct a partial order such that any element has either only finitely many predecessors or only finitely many successors, using a similar technique to that of Downey, Hirschfeldt, Lempp and Solomon [12] to prove Theorem 4.7.

Theorem 4.18.

The order type η is not computably 2-c.e.-extendible. That is, there exists a computably scattered³ computable partial order \mathcal{P} which has no computably scattered 2-c.e. linear extension.

Proof. We construct as a witness a computable partial order $\mathcal{P} = (\mathbb{N}, \leq_P)$ as the disjoint union of sub-partial orderings \mathcal{P}_e such that each \mathcal{P}_e forms a connected component of \mathcal{P} , and in particular every element of \mathcal{P}_e is incomparable to every element of every other \mathcal{P}_f where $e \neq f$.

We will assume a computable listing of 2-c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, where $R_{\langle i,j \rangle} = W_i \setminus W_j$, and an associated computable approximation $R_{\langle i,j \rangle}[s] = W_i[s] \setminus W_j[s]$. Then the purpose of \mathcal{P}_e is to show that if R_e is a linearisation of \leq_P , then there exists a computable η -sequence in R_e . By construction, such a sequence will be made up of elements of \mathcal{P}_e .

We will construct \mathcal{P}_e in such a way that every element has either only finitely many predecessors or only finitely many successors, and thus \mathcal{P}_e cannot contain any

³In fact classically scattered, as noted above.

η -sequences. Since there are no \leq_P -comparabilities between the components and each component is computably scattered, we have that \mathcal{P} as a whole is computably scattered. There is a key difference here from the proofs of Theorems 2.14 and 3.5, in that we do not need to construct \mathcal{P} such that any η -sequence in \mathcal{P} computes K , i.e. such that it is computably scattered but not necessarily scattered. We will in fact construct \mathcal{P} so that we have the stronger condition that \mathcal{P} is scattered, which simplifies the proof considerably.

At each stage s of the construction we define an approximation $\mathcal{P}[s]$ with domain some finite initial segment of \mathbb{N} , we also compute the approximations $R_e[s]$ for $e < s$. At stage 0, $\mathcal{P}[0] = \emptyset$, then at stage $s + 1$ we add up to two new elements to each $\mathcal{P}_e[s]$ with $e < s$ and four new elements to $\mathcal{P}_s[s]$.

When a number n enters the construction at a stage s , all of the \leq_P -comparabilities of n with $k < n$ are set at stage s and do not change at any later stage. So each \mathcal{P}_e is computable because if we wish to compute \leq_P relative to a pair of numbers (n, m) then it suffices to run the construction until stage $s = \max\{n, m\} + 1$ and the approximation to \leq_P relative to (n, m) at stage s will be the true value, and hence \mathcal{P} is computable.

We now fix some $e \in \mathbb{N}$ and consider the construction of \mathcal{P}_e . At all stages $s \leq e$, $\mathcal{P}_e[s] = \emptyset$, then at stage $s = e + 1$, four new elements are added to define $\mathcal{P}_e[s + 1]$, with the comparabilities $b_{-1} <_P y <_P a_{-1}$ and $b_{-1} <_P x <_P a_{-1}$ shown in Figure 4.3. We define (b_{-1}, a_{-1}) to be the *Level 1 active interval* and also to be the *Level 2 active interval*.

The labels y and x are temporary and will be reused many times during the construction for different elements before they are given a permanent label.

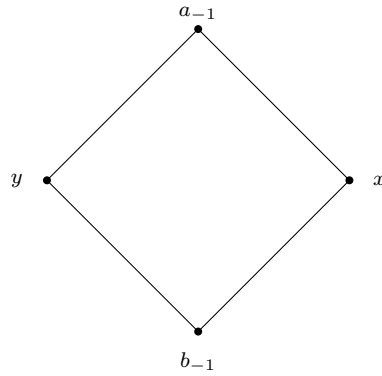


Figure 4.3: The first four elements of \mathcal{P}_e , added at stage $e + 1$

Definition 4.19.

We call a stage $s > e + 1$ a *good stage for e* if $R_e[s]$ linearises $\mathcal{P}_e[s]$. The construction of \mathcal{P}_e will only proceed at good stages for e , note that the set of good stages for e is computable.

Definition 4.20.

If s is a good stage for e , then for $m, n \in P_e[s]$ we say that $m R_e n$ is *computed at stage s* if $\langle m, n \rangle \in R_e[s]$. Since s is good for e and $R_e[s]$ is therefore a linear order, this obviously means that $\langle n, m \rangle \notin R_e[s]$.

Definition 4.21.

We say that $m R_e n$ is *1-computed at stage s* if it is computed at stage s and there is no earlier good stage at which $n R_e m$ is computed.

We say that $m R_e n$ is *2-computed at stage s* if it is computed at stage s and there is an earlier good stage at which $n R_e m$ is 1-computed.

Note that for a pair $m, n \in P_e$, $n R_e m$ can only be computed at a good stage for e , so from now on when we say that $m R_e n$ is computed (or 1-computed, 2-computed, etc) at stage s we mean by definition that s is a good stage for e .

For some R_e it may be the case that $m R_e n$ is 1-computed at stage s and there has been an earlier stage $t < s$ such that $(n, m) \in R_e[t]$, and it may even be the case that $(m, n) \in R_e[t]$ as well. However, this just means that by definition t is not a good stage for e , and hence neither $m R_e n$ or $n R_e m$ was computed at stage t .

We now consider the simple case in which there is no stage s and pair $k, l \in P_e$ such that $k R_e l$ is 2-computed at stage s . In effect we are initially proving the case for $n = 1$, which is a reproof of Corollary 4.9 (since as in the well-founded case we have that the result for computably enumerable linearisations immediately follows from the result for computably linearisations). We will then consider the case where there are 2-computed pairs, and show how the construction nests.

Now, suppose that s is the first good stage for e , and without loss of generality suppose that $y R_e x$ is 1-computed at stage s . Then relabel x as a_0 and y as b_0 , and we add two new \leq_P -incomparable elements y, x into $\mathcal{P}_e[s + 1]$ such that $b_{-1} <_P y <_P b_0$ and $b_{-1} <_P x <_P b_0$, as shown in Figure 4.4, and we define the Level 1 active interval to be (b_{-1}, b_0) .

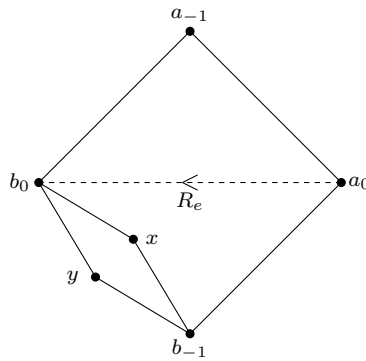


Figure 4.4: After the first good stage for e

At each subsequent good stage s for e , we will define a_i and b_i , redefine the Level 1 active

interval and add two new elements y, x . When we want to know where to put the pair y, x and the new Level 1 active interval, we use a coding similar to that in Definition 4.11. Again we create a tree of indices and an isomorphism to the standard tree of finite binary strings, as shown in Figures 4.5 and 4.6.

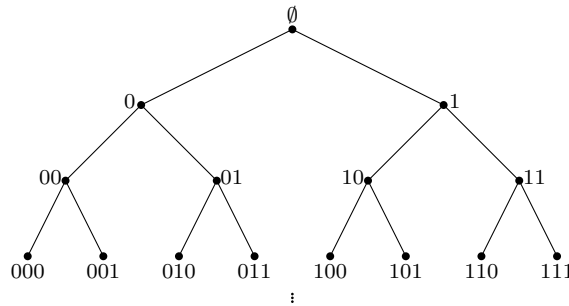


Figure 4.5: Coding of finite binary strings on a binary tree

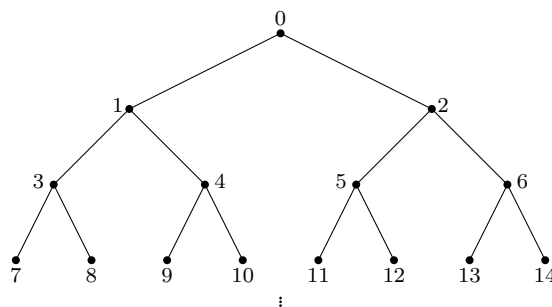


Figure 4.6: Coding of indices on a binary tree

We add 1 to the index of the last a, b pair, and find the corresponding position on the tree. Then place the pair y, x $<_P$ -above b_j and $<_P$ -below a_k , where j is the first index above and to the left on the tree, and k is the first index above and to the right on the tree. Using either j or k is -1 if they don't exist.

In Figure 4.7 we see what \mathcal{P}_e looks like after several good stages, notice the how we can see the η pattern of pairs building up. The next Level 1 active interval (b_{-1}, b_7) is marked by a dotted line, where the next y, x pair will be added.

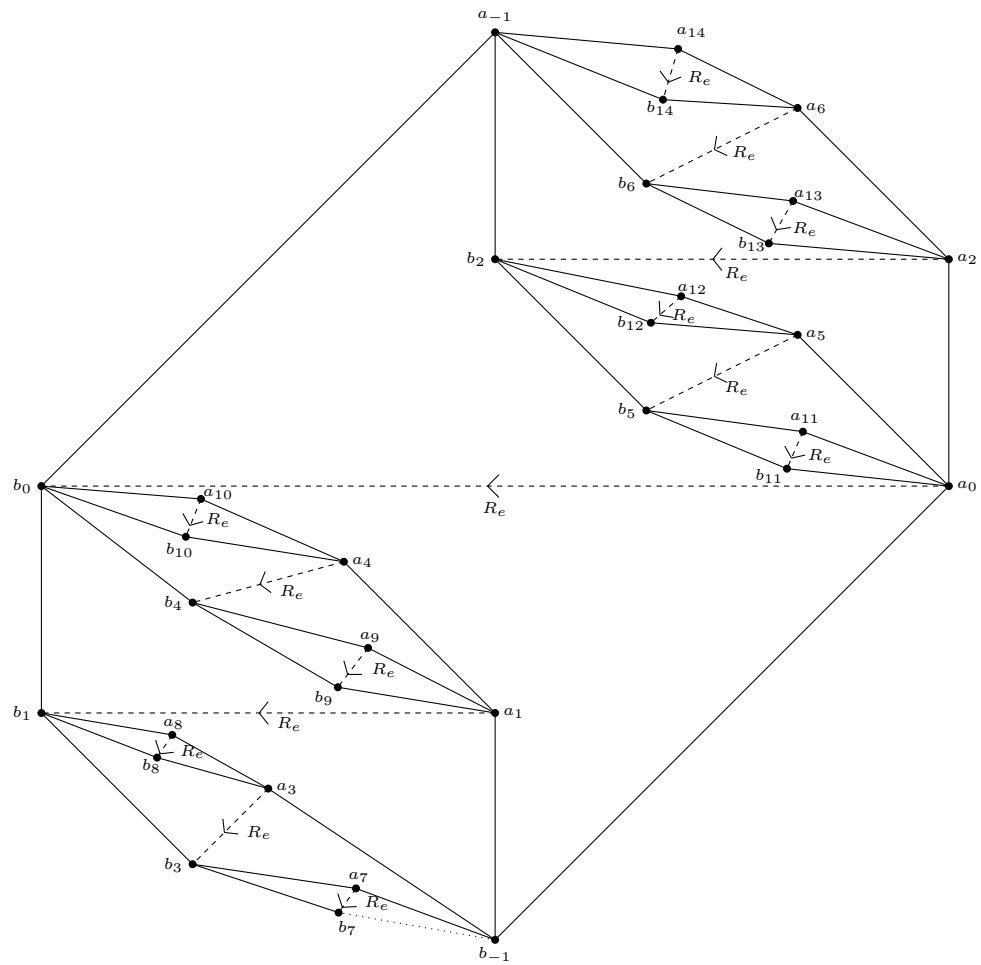


Figure 4.7: After the first few stages

If there are only finitely many good stages, then \mathcal{P}_e will be finite, and the necessary conditions for the theorem trivially hold, as it contains no η -sequence, and R_e is not a linearisation of \mathcal{P}_e . Indeed if R_e is a linearisation of \mathcal{P}_e then there will be infinitely many good stages for e , at which elements were added to \mathcal{P}_e and \mathcal{P}_e would be infinite.

If there are infinitely many good stages for e and \mathcal{P}_e is therefore infinite, still under the supposition that there is no pair which is ever 2-computed, then the sequence $\{a_n\}_{n \in \mathbb{N}}$ forms a computable dense suborder of R_e , but not of \mathcal{P}_e . This is because any given a_n

has finitely many elements \leq_P below it, since once a_n is defined, at no stage will any new element be enumerated into \mathcal{P}_e directly below a_n .

We note that similarly for the b_n , once they are defined there will not be any new elements placed directly above b_n , and so every element of \mathcal{P}_e has either finitely many elements above it or below it, and therefore \mathcal{P}_e is scattered.

If R_e linearises \mathcal{P}_e , then we can find a computable η -sequence in R_e . In fact by construction, $\{a_n\}_{n \in \mathbb{N}}$ is a computable η -sequence in R_e , which will be infinite as we know that R_e linearising \mathcal{P}_e means that \mathcal{P}_e will be infinite, and therefore R_e is not computably scattered. This concludes the proof of the simpler case in which there is no pair which is ever 2-computed.

Now, suppose that in fact there is at least one pair $n, m \in P_e$ such that $n R_e m$ is 2-computed at some stage s . Note that without loss of generality we can in fact assume that the 2-computed pair is a_n, b_n for some n , because it is clear by inspection of the construction that if any pair is 2-computed then there will be some a_n, b_n that is 2-computed. Thus during the construction below we only need to search for the least index k such that $b_k R_e c_k$ is 2-computed at stage $s + 1$.

So, suppose we are at the first stage at which any a_n, b_n is 2-computed, and suppose that n is the least index of a 2-computed pair. Then we relabel a_n as b'_0 , b_n as a'_0 and add two new numbers y', x' to $P_e[s + 1]$ such that $b_{-1} <_P y' <_P b'_0$ and $b_{-1} <_P x' <_P b'_0$. Then we define (b_{-1}, b'_0) to be the Level 1 active interval and also the Level 2 active interval. We then restart the Level 1 construction inside the Level 2 active interval.

The Level 1 construction then restarts from scratch in the new Level 1 interval, building a new a_n sequence until such a time as there is another stage t at which some

pair is 2-computed. As further pairs are 2-computed, we do the same thing, labelling them as a'_i, b'_i and then restarting the Level 1 construction in the new Level 2 interval, which is defined in the correct place using the same coding as in the Level 1 construction to so that the 2-computed pairs as they appear, form an η -sequence.

The construction continues as above. We see that if there are only finitely many stages at which the Level 2 active interval is redefined, then from some stage s all activity in the construction will be at Level 1, and we get the same outcome as in the first case. Namely that if R_e is a linearisation of \mathcal{P}_e then there is a computable dense suborder in R_e , and by construction the a_n form such a suborder. And \mathcal{P}_e is still constructed to be scattered.

Alternatively the Level 2 active interval may be redefined infinitely many times, or in other words there may be infinitely many stages at which there is a 2-computed pair. But then the $\{a'_n\}_{n \in \mathbb{N}}$ form a computable dense suborder of R_e .

To show that $\{a'_n\}_{n \in \mathbb{N}}$ is a computable sequence, notice that the pairs (a'_n, b'_n) which are 2-computed, can be found by a uniformly computable search, and hence there is an algorithm which computes the sequence of such pairs in order, and therefore also computes a'_0, a'_1, a'_2, \dots

We see that \mathcal{P} is still scattered because any element either has only a finite number of elements above it or below it in \mathcal{P} .

Since e was arbitrary, we see that \mathcal{P} has no computably scattered 2-c.e. linear extension, and \mathcal{P} is scattered. But we have also seen that the construction of \mathcal{P} is entirely computable. This concludes the proof of Theorem 4.18. \square

Corollary 4.22.

The order type η is not computably n -c.e.-extendible for any $n \geq 1$. That is, for every $n \geq 1$, there exists a scattered computable partial order \mathcal{P} which has no computably scattered n -c.e. linear extension.

Proof. A computably enumerable (1-c.e.) linearisation of \mathcal{P} will be computable. We proved the $n = 1$ case as the first part of the proof for $n = 2$, and of course the partial order constructed by Downey et. al. as a witness to Theorem 4.7 also proves this case. We now show how to generalise the proof of the $n = 2$ case above to any $n \in \mathbb{N}$.

Consider the $n = 3$ case. We perform the construction as with $n = 2$, but with an extra layer, the construction can now define Level 3 active intervals. When a Level 3 active interval is defined or redefined all Level 2 and Level 1 construction is restarted from scratch in the new Level 3 interval. At Level 3 we will be building a computable η -sequence a''_n in R_e , when pairs b''_n, c''_n are 3-computed.

We will assume a computable listing of 3-c.e. sets, $\{R_e\}_{e \in \mathbb{N}}$, where $R_{\langle i,j,k \rangle} = (W_i \setminus W_j) \cup W_k$, and an associated computable approximation $R_{\langle i,j,k \rangle}[s] = (W_i[s] \setminus W_j[s]) \cup W_k[s]$. We define 3-computation in the obvious way, we say that $m R_e n$ is *3-computed at stage s* if it is computed at stage s and there is an earlier good stage at which $n R_e m$ is 2-computed. And in general, if R_e is a k -c.e. set, then we say that $m R_e n$ is *r -computed at stage s* , for some $r \leq k$, if it is computed at stage s and there is an earlier good stage at which $n R_e m$ is $r - 1$ -computed and there is no earlier good stage at which $n R_e m$ is $r + 1$ -computed.

Then the construction in the case where there is 3-computation works in the same way relative to 2-computation as 2-computation works relative to 1-computation. For example when the first pair is 3-computed this is because a 2-computed pair (b'_n, a'_n) has

been found such that $b'_n R_e a'_n$ is 3-computed at this stage s (and n is the least index of such a pair). Then we enumerate new elements x, y and redefine $b''_0 = a'_n$ and $a''_0 = b'_n$, as shown in Figure 4.8.

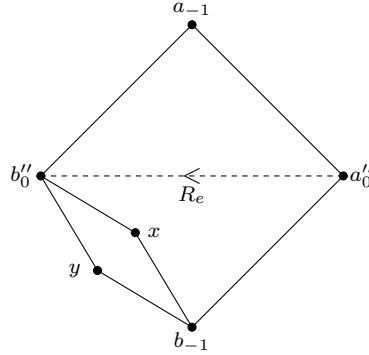


Figure 4.8: After the first pair is 3-computed

Then the construction at Level 2 and Level 1 restarts from scratch in the new Level 3, 2 and 1 active interval (b''_0, a''_0) . It behaves as a nested version of the construction in the Theorem above, but with the difference that the Level 3 active interval can be redefined either finitely or infinitely often.

We take the greatest $t \in \{1, 2, 3\}$ such that the Level t active interval is redefined infinitely often. If the Level 3 active interval is redefined infinitely often then if R_e linearises \mathcal{P}_e then we define a sequence of a''_n which will be a computable η -sequence in R_e . If it is redefined only finitely often, then after some finite stage it will be fixed, and the remainder of the construction will be at Level 2 and Level 1. So the outcomes are the same as in the $n = 2$ case, either the a'_n defined form a computable η -sequence in R_e (if R_e linearises \mathcal{P}_e), or after a finite time there is only Level 1 activity, and the a_n form a computable η -sequence in R_e (if R_e linearises \mathcal{P}_e).

The case for n -c.e. is then a straightforward generalisation of this, take a computable listing of n -c.e. sets R_e and associated approximations $R_e[s]$, and define n -computation

as above. Work through the construction as in the $n - 1$ case, but when something is n -computed we define the points $a_i^{(n-1)}, b_i^{(n-1)}$ and redefine the Level n active interval. There will then be some $1 \leq t \leq n$ such that the Level t active interval is redefined infinitely often. Then if t is the greatest of those, if R_e linearises \mathcal{P}_e then the $\{a_n^{t-1}\}_{n \in \mathbb{N}}$ will be a computable η -sequence in R_e .

Then for any n we can construct a witness \mathcal{P} which is computable and computably scattered, but has no computably scattered n -c.e. linearisation. \square

Again, we note that this construction fails for ω -c.e., because if there is no fixed bound on the number of times a pair can be changed in the linearisation, then there will not necessarily be a greatest t such that the Level t active interval is redefined infinitely often. In fact we could have no such t and just keep redefining intervals of greater and greater Level, but only finitely often. Thus we cannot build the computable η -sequence necessary in R_e and the argument fails.

As in the previous chapter, we could have proved this by building one witness which proves the theorem for all $n \geq 1$, rather than constructing a separate counterexample for each $n \geq 1$. To do this, we need a listing of all n -c.e. sets, for all $n \geq 1$, which we define $\{R_{\langle n, e \rangle}\}_{n, e \in \mathbb{N}}$ with uniform approximations $\{R_{\langle n, e \rangle}[s]\}_{n, e, s \in \mathbb{N}}$.

Let $g : \mathbb{N}^3 \rightarrow \mathbb{N}$ be a computable function such that

$$W_{g(n, e, k)} = \begin{cases} \bigcap_{0 \leq i \leq k} W_{e_i} & \text{if } 0 \leq k \leq n \text{ (where } e = \langle e_0, e_1, \dots, e_{n-1} \rangle), \\ \emptyset & \text{if } k > n. \end{cases}$$

Note that n determines the length of the tuple coded as e , and if $n = 0$ then we use the convention that $e = \langle e \rangle$, so $e_0 = e$.

Then

$$R_{\langle n,e \rangle} = \bigcup_{i=0}^{\lfloor \frac{n}{2} \rfloor} W_{g(n,e,2i)} \setminus W_{g(n,e,2i+1)},$$

and $R_{\langle n,e \rangle}[s]$ is defined using the stage s approximations to all the of c.e. sets involved.

The construction then proceeds in the usual way, with $\mathcal{P}_{\langle e,n \rangle}$ being the component of the witness which shows that if $R_{\langle e,n \rangle}$ is a linearisation of \mathcal{P} then there exists a computable η -sequence in $R_{\langle e,n \rangle}$. Notice that because n is encoded in the index of $\mathcal{P}_{\langle e,n \rangle}$, we can computably determine which algorithms from the above proofs to use in the construction, and hence the construction remains computable. In effect we simultaneously perform the constructions for the proof for each $n \geq 1$.

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